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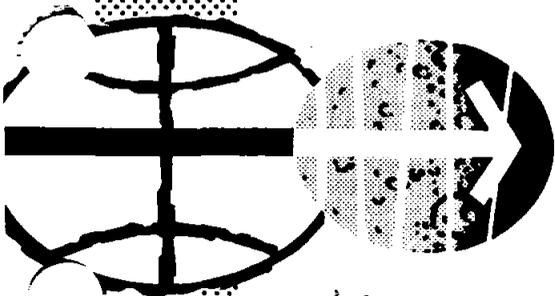
APOLLO 11 FLIGHT PLAN

AS-506/CSM-107/LM-5

*Book
use in Review*

APRIL 15, 1969

PREPARED BY
FLIGHT PLANNING BRANCH
FLIGHT CREW SUPPORT DIVISION



MANNED SPACECRAFT CENTER
HOUSTON, TEXAS

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SECTION II
SECTION III
SECTION IV
SECTION V

APOLLO 11
APOLLO AS-506/CSM-107/LM-5
PRELIMINARY FLIGHT PLAN

APRIL 15, 1969

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INTRODUCTION

This Flight Plan has been prepared by the Flight Planning Branch, Flight Crew Support Division, with technical support by TRW Systems.

This document schedules the AS-506/CSM-107/LM-5 operations and crew activities to fulfill, when possible, the test objectives defined in the Mission Requirements, G Type Mission Lunar Landing to be published.

The trajectory parameters used in this Flight Plan are for July 16, 1969 launch, with a 72° launch azimuth and were supplied by Mission Planning and Analysis Division as defined by the Apollo Mission G Spacecraft Operational Trajectory to be published.

The Apollo 11 Flight Plan is under the configuration control of the Crew Procedures Control Board (CPCB). All proposed changes to this document that fall in the following categories should be submitted to the CPCB via a Crew Procedures Change Request:

1. Items that impose additional crew training or impact crew procedures.
2. Items that impact the accomplishment of detailed test objectives.
3. Items that result in a significant RCS or EPS budget change.
4. Items that result in moving major activities to a different activity day in the Flight Plan.
5. Items that require a change to the flight data file.

The Chief, Flight Planning Branch (FCSD) will determine what proposed changes fall in the above categories.

Mr. T. A. Guillory will act as co-ordinator for all proposed changes to the Apollo 11 Flight Plan.

Any requests for additional copies or changes to the distribution lists of this document must be made in writing to Mr. W. J. North, Chief, Flight Crew Support Division, MSC, Houston, Texas.

ABBREVIATIONS

ACCEL	Accelerometer	EQUIP	Equipment	L/V	Local Vertical	Rxx	Routine XX
ACN	Ascension	EST	Eastern Standard Time	LVPD	Launch Vehicle Pressure Display	SA	Shaft Angle
ACT	Activation	EVA	Extravehicular Activity	M	Mandatory	S/C	Spacecraft
ACQ	Acquisition	EVAP	Evaporator	MAO	Madrid, Spain	SCF	Signal Conditioning Equipment
AEA	Abort Electronics Assembly	EVT	Extravehicular Transfer	MAN	Manual	SCS	Stabilization Control System
AGS	Abort Guidance Subsystem	EXT	External	MAX	Maximum	SCT	Scanning Telescope
AH	Ampere Hours	f	F Stop	MAX Q	Maximum Dynamic Pressure	SEC	Secondary
ALT	Altitude	FC	Fuel Cell	MCC	Midcourse Correction	SECO	S-IVB Engine Cut-off
AMP or amp	Ampere	FDAI	Flight Director Attitude Indicator	MCC-H	Mission Control Center - Houston	SEP	Separate
AMPL	Amplifier	FLT	Flight	or MCC		SEQ	Sequence
ANG	Antigua	FM	Frequency Modulated	MDC	Main Display Console	SIVB	Saturn IV B (Third Stage)
Ant	Antenna	FOV	Field of View	MEAS	Measurement	SILA	Service Module LM Adapter
AOH	Apollo Operations Handbook	FPS or FPS	Feet per second	MER	USNS Mercury	SLOS	Star Line-of-Sight
AOS	Acquisition of Signal or Acquisition of Site	FT or ft	Feet	NET	Mission Event Timer	SM	Service Module
AOT	Alignment Optical Telescope	FTP	Full Throttle Position	MGA	Middle Gimbal Angle	SPOT	Spot Meter
APS	Ascent Propulsion Subsystem			N/I	Minimum Impulse	SPS	Service Propulsion System
ARS	Atmosphere Revitalization	GBI	Grand Bahama Islands, Eastern Test Range	MIN	Minimum	SR	Sunrise
ATT	Attitude	GBM	Grand Bahama (MSFM)	MLA	Merritt Island, Florida	SRC	Sample Return Container
AUX	Auxiliary	GDC	Gyro Display Coupler	MNVR	Maneuver	SRX	S-Band Receiver Mode No. X
AZ	Azimuth	GDS	Goldstone, California	MPS	Main Propulsion System	SS	Sunset
BAT	Battery	GET	Ground Elapsed Time	MSFN	Manned Space Flight Network	STX	S-Band Transmit Mode No. X
BOA	Bermuda	GETI	Ground Elapsed Time of Ignition	MTVC	Manual Thrust Vector Control	SMC	Solar Wind Component
BIO	Bio-Medical Data on Voice Downlink	GLY	Glycol	N2	Nitrogen	SW	Switch
BP	Barber Pole	GMT	Greenwich Mean Time	NAV	Navigation	SXT	Sextant
BT	Burn Time	GSN	Guidance and Navigation	NCC	Corrective Combination Maneuver	T	Time of Ephemeris Update
BU	Backup	GNCS	Guidance Navigation Control System	nm	Nautical Miles	TA	Tranunion Angle
B&W	Black & White	GMM	Guam	NDM	Nominal	TAN	Tanarive, Madagascar
BRKT	Bracket	GYM	Guaymas, Mexico	NSR	Nominal Slow Rate	TB	Time Base No.
CAP COM	Capsule Communicator	H2	Hydrogen	NXX	Noun XX	(x)	
CAL θ	Calibration Angle	HA	Apogee Altitude	O2	Oxygen	TCA	Time of Closest Approach
CAM	Camera	HAW	Hawaii	OBS	Observation	TDBE	Transposition Docking & LM Ejection
CB	Circuit Breaker	HBR	High Bit Rate (TLM)	O/F	Oxidizer to Fuel Ratio	TEC	Trans Earth Coast
CDH	Constant Delta Altitude	HD	Highly Desirable	OGA	Outer Gimbal Angle	TEI	Transearth Insertion
CDR	Commander	HGA	High Gain Antenna	OMNI	Omnidirectional Antenna	TEMP	Temperature
CDU	Coupling Data Unit	HI	High	OPS	Oxygen Purge System	TERM	Terminate
CIRC	Circularization	Hp	Perigee Altitude	ORB	Orbital	TEX	Corpus Christi, Texas
CK	Check	HSK	Honeyuckle (Canberra, Australia)	ORDEAL	Orbit Rate Display Earth and Lunar	TGT	Target
CM	Command Module	HTR	Heater	ORIENT	Orientation	TIG	Time of Ignition
CMC	Command Module Computer	HTV	USNS Huntsville	OVHD	Overhead	TLC	Trans Lunar Coast
CONT	Continue	ICDU	Inertial Coupling Data Unit	P	Pitch	TLI	Translunar Insertion
CMD	Command	IO	Identification	PAD	Pulse Update	TLM	Telemetry
CMP	Command Module Pilot	IGN	Ignition	PCM	Pulse Code Modulation	TPF	Terminal Phase Final
CNL	Control	IMU	Inertial Measurement Unit	PC	Pericyynthion	TP1	Terminal Phase Initiation
C/O	Check out	INIT	Initialization	PGA	Pressure Garment Assembly	TPM	Terminal Phase Midcourse
COAS	Crew Optical Alignment Sight	INT	Intervolometer	PGNCS	Primary Guidance Navigation Control Section	T/R	Transmitter/Receiver
COMM	Communications	IP	Initial Point	PIPA	Pulse Integrating Pendulous Accelerometer	TRANS	Translation
CONFIG	Configuration	IU	Instrumentation Unit	PLSS	Portable Life Support Systems	TVC	Thrust Vector Control
CONT	Continue	IVC	Intervehicular Communications	PM	Phase Modulated	TWR	Tower
CP	Control Point	IVT	Intravehicular Transfer	POL	Polarity or Polarizing	UMB	Umbilical
CRO	Carnarvon, Australia	JETT	Jettison	PRE	Pretoria, South Africa	UNDK	Undock
CRYO	Cryogenic	kwh	Kilowatt Hour	PREP	Preparation	US	United States Pass
CSI	Coelliptic Sequence Initiation Maneuver	LA	Launch Azimuth	PRESS	Pressure	V	Velocity
CSM	Command Service Module	LAT	Latitude	PROP	Proportional	VAN	USNS Vanguard
C&WS	Caution and Warning System	LBR	Low Bit Rate (TLM)	PU	Proportional Utilization	VHF	Very High Frequency
CYI	Grand Canary Island	LBS or lbs	Pounds	PUGS	Propellant Utilization and Gaging System	VLV	Valve
DAP	Digital Auto Pilot	LCG	Liquid Cooled Garment	PTC	Passive Thermal Control	VI	Inertial Velocity
D/B	Deadband	LDG	Landing	PHR	Power	VDX	Voice Keying
DCA	Digital Command Assembly	LDMK	Landmark	Pxx	Program XX	Vxx	Verb xx
DEDA	Data Entry and Display Assembly	LEB	Lower Equipment Bay	Qty	Quantity	W/O	Without
DEGS	Degrees	LFB	Lunar Far Horizon	R	Roll/Range	WRT	With Respect to
DFPL	Depletion	LGC	LM Guidance Computer	R&B	Red & Blue	WTN	USNS Watertown
DET	Determination or Digital Event Timer	LH	Left-hand	RAD	Radiator	XFER	Transfer
DIFF	Difference	L/H	Left-hand Horizontal	RCDR	Recorder	XMIT	Transmit or Transmitter
DK	Dock or Docked	LHEB	Left-hand Equipment Bay	RCS	Reaction Control System	XPONDER	Transponder
DOI	Descent Orbit Insertion	LHFB	Left-hand Forward Equipment Bay	RCU	Remote Control Unit	Y	Yaw
DPS	Descent Propulsion Subsystem	LHSSC	Left Hand Side Storage Container	REV	Receiver	AV	Velocity Change (Differential)
DSE	Data Storage Equipment	LHYD	Lithium Hydroxide	REU	USNS Redstone	AVC	Velocity Change at Engine Cutoff
DSFY	Display and Key Board	LIM	Lunar Landing Mission	REFSMAT	Reference Stable Member Matrix	AR	Position Change (Differential)
DTO	Detailed Test Objective	LLOS	Landmark Line of Sight	REG	Regulator	B-Balls	Flight Director Attitude Indicator (FDI)
DUP	Digital Uplink Assembly	LM	Lunar Module	REQD	Required	X	CSM TCA
DWN	Down	LMP	Lunar Module Pilot	RH	Right-hand		
E	Erasable	LNI	Lunar Near Horizon	PLS	Radius of Lunar Site		
EASG	Early Apollo Scientific Equipment Package	LOI	Lunar Orbit Insertion	PLZ	Rendezvous		
ECS	Environmental Control System	LONG	Longitude	RPLZ	Rendezvous Radar		
EHI	Earth Far Horizon	LOS	Loss of Signal or Loss of Site	RST	Roll Stability Indicator		
EI	Earth (atmosphere) Interface	LPO	Lunar Parking Orbit	RT	Real Time		
EL	Elevation	LR	Landing Radar	RTG	Radioisotope Thermoelectric Generator		
ELM	Earth Landmark	LT	Light				
EMG	Entry Monitor System	LTC	Lighting				
EHZ	Earth Far Horizon	LV	Launch Vehicle				
EPL	Earth Parking Orbit						
EM	Electronics Management Subsystem						

SECTION I - GENERAL

MISSION DESCRIPTION

1. Launch and E.P.O. (Duration 2:44) T_0 - 2:44 GET

- (a) Nominal launch time is 8:32 EST, July 16, 1969, with a launch window duration of 4 hrs. 24 min.
- (b) Earth orbit insertion into a 100 nm circular orbit at 11 min. 24 sec. after lift-off
- (c) CSM systems C/O in earth orbit
- (d) Optional IMU realign (P52) to the pad REFSMMAT during the first night period
- (e) TLI occurs at 2:44:18 GET over the Pacific Ocean during the second revolution. (See Table 1-1 for burn data).

2. Translunar Coast (Duration 73:11) 2:44 - 75:55 GET

After TLI, which places the spacecraft in a free lunar return trajectory, the following major events occur prior to LOI:

- (a) Transposition, docking and LM ejection, including SIVB photography
- (b) Separation from SIVB and a CSM evasive maneuver
- (c) SIVB propulsive venting of propellants (slingshot)
- (d) Two series of P23 cislunar navigation sightings, star/earth horizon, consisting of five sets at 06:00 GET and five sets at 24:00 GET
- (e) Four midcourse corrections which take place at TLI + 9, TLI + 24, LOI - 22 and LOI - 5 hours with ΔV nominally zero (See Table 1-1).
- (f) Passive thermal control (PTC) will be conducted during all periods when other activities do not require different attitudes.
- (g) LM inspection and housekeeping
- (h) LOI_1 , performed at 75:55:03 GET, ends the TLC phase.

3. Lunar Orbit (Duration 55:38) 75:55 - 131:33 GET

LOI Day

- (a) LOI₁
- (b) Photos of targets of opportunity
- (c) LOI₂
- (d) Post LOI₂ LM entry and inspection. Ten minutes of VHF-B LBR data will be transmitted to CSM/DSE for playback to MSFN.
- (e) Post LOI₂ Pseudo landmark tracking (one set of sightings)
(See Table 1-3)
- (f) Rest period of 8 hours

4. Descent and Landing Day (Duration 23:48) 94:32 - 118:20 GET

- (a) Docked LM activation and checkout
- (b) Docked landing site landmark sighting (one set of sightings)
(See Table 1-3)
- (c) Undocking and separation (See Figure 1-3 Rendezvous Profile)
- (d) DOI thru landing
- (e) LM post touchdown and simulated liftoff
- (f) Rest period (LM) of 4 hours
- (g) CSM plane change
- (h) Rest period (CSM) of 4 hours

5. LUNAR EXPLORATION DAY (Duration 10:30) 109:30 - 12:00 GET

- (a) EVA prep
- (b) EVA for 2 hours 40 minutes
- (c) Post EVA
- (d) Rest period (LM) 4 hours 40 minutes
- (e) Rest period (CSM) 4 hours

6. Lift-Off, Rendezvous & TEI Day (Duration 17:00) 122:28 - 139:28 GET

- (a) LM Lift-Off and Insertion

- (b) LM active rendezvous
 - CSI
 - PC
 - CDH
 - TPI
- (c) Docking
- (d) LM jettison
- (e) TEI
- (f) Rest Period

7. Lunar Orbit Particulars (Average Values for a 60 x 60 nm orbit)

- (a) Revolutions start at 180° longitude
- (b) Revolution duration - 1 hr. 58.2 min.
- (c) S/C night period duration - 47 min.
- (d) MSFN coverage per rev. - 72 min.
- (e) Orbit inclination - 1.25° for July 16, 1969 launch
- (f) S/C orbital rate - $3^{\circ}/\text{min}$. ($.05^{\circ}/\text{sec}$)
- (g) Lighting change at fixed ground point - $1^{\circ}\text{West}/\text{Rev}$.
- (h) Ground track change - $1^{\circ}\text{West}/\text{Rev}$. at equator
- (i) Horizon visibility $\pm 20^{\circ}$ selenocentric angle on the lunar surface
- (j) One lunar degree on lunar surface is 16.38 nm.
- (k) Site 2 will be visible (3° sun angle) at REV. 7
- (l) S/C sublunar point to horizon 320 nm.

8. Transearth Coast and Entry (Duration 63:38) 131:29 - 195:07 GET

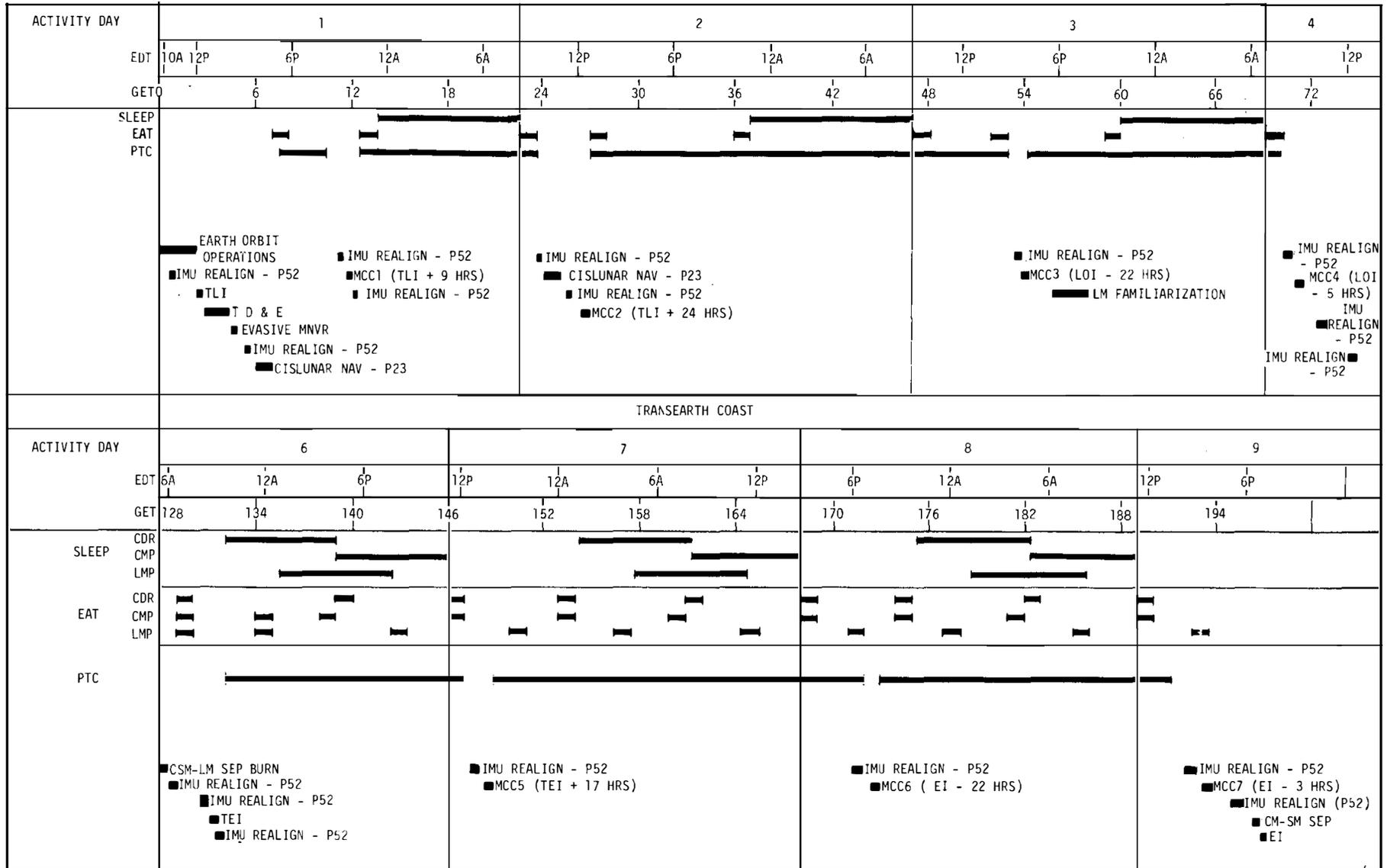
Transearth coast begins with TEI at 131:28:43 GET and consists of the following major events:

- (a) Three midcourse corrections are scheduled at TEI + 17, EI - 22 and EI - 3 hours with ΔV nominally zero.
- (b) CM/SM separation takes place at 194:51 GET and Entry Interface occurs at 195:06 GET.

- (c) Splashdown will occur in the Pacific Ocean at a longitude of about 165° west at 195:21 GET. This will occur approximately 15 minutes prior to sunrise local time.
- (d) During TEC the crew will follow a staggered rest period so that at least one crewman will be awake to monitor PTC.

FIGURE 1-1

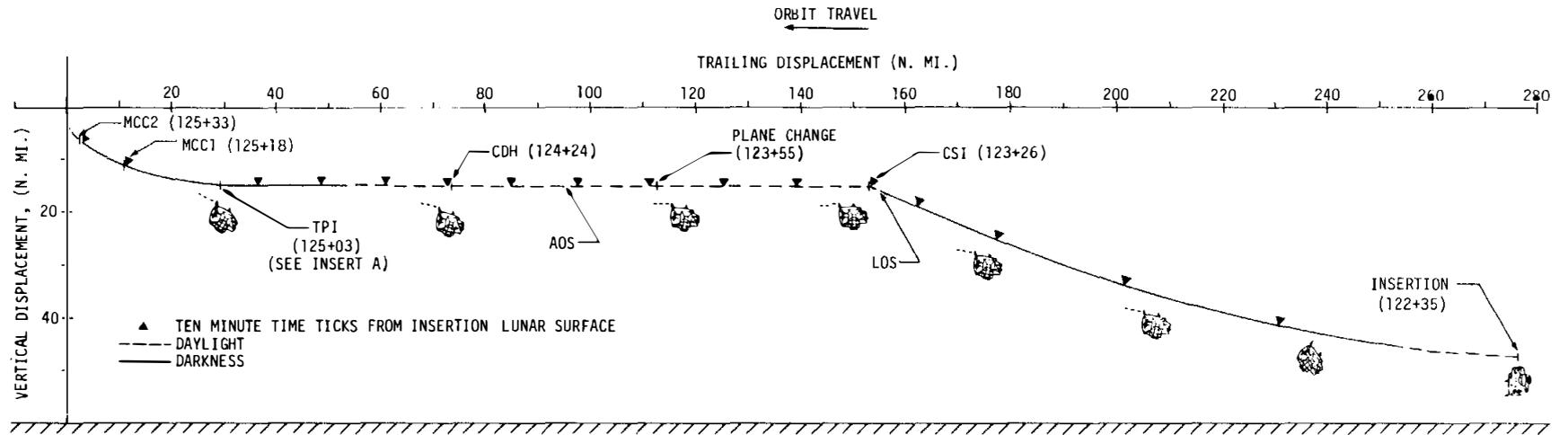
MISSION SUMMARY FLIGHT PLAN
(TRANS LUNAR COAST)



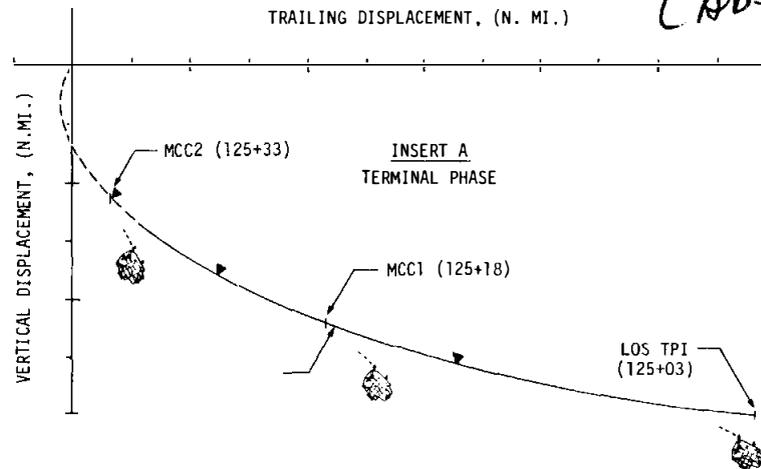
LUNAR ORBIT SUMMARY FLIGHT PLAN FIG. 1-2

ACTIVITY DAY	4 (LOI DAY)												5 (DOI AND EVA DAY)												6 (ASCENT & TEI)											
SLEEP	[SLEEP]												[SLEEP]												[SLEEP]											
EDT	12AM	04PM	08PM	12PM	04AM	08AM	12AM	04PM	08PM	12PM	04AM	08AM	12AM	04PM	08PM	12PM	04AM	08AM	12AM	04PM	08PM	12														
GET	74	76	78	80	82	84	86	88	90	92	94	96	98	100	102	104	106	108	110	112	114	116	118	120	122	124	126	128	130	132	134					
REVOLUTION NO.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30						
LM	OPEN HATCH, LM IVT TO LM LM STATUS CHECK, 10 MIN VHF B LBR DATA RECEIVE & STOW EQPT LM IVT TO CSM CLOSE HATCH												CDR-LMP IVT TO LM ACTIVATE EPS ECS ACTIVATION & CHECKOUT ACTIVATE PNGCS S-BAND STEERABLE CHECKOUT LMP IVT TO CSM DON LGC & PGA IVT TO LM E MEMORY DUMP MANUAL IMU ALIGN ASSIST CDR CLOSE LM HATCH DON HELMET & GLOVES ARS/PGA CHECK CABIN REG CHECK RATE GYRO CHECK AGS ACT & SELF TEST RCS, DPS & AGS CHECKS RR ACT & CHECKOUT DPS PRESS AGS ACCEL & GYRO CK DEPLOY LANDING GEAR UNDOCK RR & VHF RANGING & CHECKOUT IMU REALIGN P52 & SYSTEMS CHECKS LR SELF TEST DOI ATTITUDE & SYSTEMS CHECKS PDI TOUCHDOWN POST TOUCHDOWN CHECKS												DECISION TO STAY ONE CSM REV SIMULATED COUNTDOWN CAL AGS GYROS IMU REALIGN P57 GRAVITY AGS LUNAR ALIGN IMU REALIGN P57 OPT 2 IMU REALIGN OPT 3 LUNAR STAY DECISION SELECT P12, ASCENT RR TRACK OF CSM EAT PERIOD						AGS AND PNGCS TURN ON & SELF TEST RR SELF TEST IMU REALIGN P51 REFSMMAT T-ALIGN RR TRACK CSM EAT PERIOD APS PRESSURIZE IMU REALIGN P57, ENTER P12, ASCENT SYSTEMS CHECKS LIFTOFF INSERTION IRR SELF TEST IMU REALIGN P52 RR TRACK OF CSM CSI BURN - RCS PLANE CHANGE BURN - RCS CDH BURN - RCS TPI BURN - RCS MCC1 BURN RCS MCC2 BURN RCS TPF BURN RCS BRAKING BURNS - RCS DOCKING TRANSFER & STOW CLOSE OUT LM					
	NOTE: THE LM IS PRESSURIZED DURING THE TRANSLUNAR COAST PERIOD																																			
CSM	LOI - 1 IMU REALIGN P52 IMU REALIGN P52 LOI - 2 TRANSFER EQPT TO LM LANDMARK TRACKING EAT (ALL)												EAT (ALL) IMU REALIGN P52 DROGUE INSTALLATION CLOSE CSM HATCH LDG SITE LDMK TRACK DON HELMET & GLOVES UNDOCK INSPECT LM CSM SEPARATION IMU REALIGN P52 DUMP DSE SXT TRACK LM/VHF RANGING IMU REALIGN P52 SXT TRACK LM IMU REALIGN P52 (PULSE TORQUE) EAT PERIOD PLANE CHANGE IMU REALIGN P52												EAT PERIOD IMU REALIGN P52 SXT TRACK LM VHF RANGING IMU REALIGN P52 BACKUP LM CSI BURN BACKUP LM CDH BURN MONITOR MCC & BRAKING DOCKING TRANSFIGURE & STOW EQPT PREP FOR LM JETTISON LM SEP BURN + JETTISON IMU REALIGN P52 EAT PERIOD SYSTEMS CHECKS IMU REALIGN P52 TEI PREP TEI BURN											
SLEEP	[SLEEP]												[SLEEP]												[SLEEP]											
GET	74	76	78	80	82	84	86	88	90	92	94	96	98	100	102	104	106	108	110	112	114	116	118	120	122	124	126	128	130	132	134					

FIGURE 1-3



1-7



G1 MISSION RENDEZVOUS
(CSM-CENTERED RELATIVE MOTION)

PREPARED BY STEPHEN P. GREGA
ORBITAL PROCEDURES SECTION

TABLE I-1 CSM BURN SCHEDULE

BURN/MANEUVER	GETI BURN TIME AVC	ATTITUDE (DEG)		LIGHTING	ΔV (FPS)	ULLAGE ΔV (FPS)	TVC MODE	REFSMAT	ΔV RESULT (SC WT, HP, HA)	REMARKS
		LH/LV	INERTIAL							
S-IVB TLI	2:44:18 5MIN 21 SEC	R: P: Y:	R: P: Y:	BURNOUT AT SUNRISE	ΔVX: ΔVY: ΔVZ: ΔV REQ: 10,446	—	—	PAD	WT: HP: HA:	S-IVB BURN
CSM/LM S-IVB EVASIVE MNR	4:39:37 3 SEC	R:180 P:282.6 Y: 1.9	R:180.2 P:118.8 Y:329.6	SUNLIGHT	ΔVX: 5.1 ΔVY: 0.0 ΔVZ: 19.0 ΔV REQ: 19.7	NOT REQUIRED	G&N AUTO	PAD	WT:96807 HP: HA:	SPS BURN
MIDCOURSE CORRECTIONS MCC ₁ to MCC ₄	11:24 26:44 53:55 70:55	R:- P:- Y:-	R:- P:- Y:-	---	ΔVX: NOMINALLY ΔVY: ZERO ΔVZ: ΔV REQ:	NOT REQUIRED	G&N AUTO	PAD PTC PTC LDG SITE		TLI + 9 TLI + 24 LOI - 22 LOI - 5
LOI ₁	75:55:03 6 MIN 5 SEC	R:357.9 P:165.4 Y:349.6	R:357.9 P:227.1 Y:345.1	DAYLIGHT (SS-1HR 8 MIN)	ΔVX: -2892.8 ΔVY: - 425.9 ΔVZ: - 50.3 ΔV REQ: -2924.4	NOT REQUIRED	G&N AUTO	LDG SITE	WT:95013.8 HP:60 HA:170	SPS BURN
LOI ₂	80:12:01 14 SEC	R: 0 P:182.1 Y:357.6	R: 13.3 P:239.3 Y:357.6	DAYLIGHT (SR+14 MIN)	ΔVX: -138.5 ΔVY: 0 ΔVZ: - 70.8 ΔV REQ: -138.5	2 Jet 14 Sec fps	G&N AUTO	LDG SITE	WT:71148.9 HP: 60 HA: 60	SPS BURN
CSM/LM SEP	98:43:14 7 SEC	R: 0 P:269.8 Y: 0	R: 0 P:193.6 Y: 0	SUNLIGHT (SS-14 MIN)	ΔVX: 0 ΔVY: 0 ΔVZ: 2.5 ΔV REQ: 2.5	—	G&N AUTO	LDG SITE	WT:36276.2 HP: HA:	RCS BURN
CSM PLANE CHANGE	105:09:17 1 SEC	R:276.2 P:263.9 Y: 88.2	R:276.2 P: 95.6 Y: 88.3	DARKNESS (SS+16 MIN)	ΔVX: 0 ΔVY: 16.5 ΔVZ: 0 ΔV REQ: 16.5	2 Jet 19 Sec fps	G&N AUTO	PLANE CHANGE	WT:36264.9 HP: HA:	SPS BURN
LM JETTISON	128:24:26 3 SEC	R: 0 P: 180 Y: 0	R: 0 P: 84.5 Y: 0	DAYLIGHT (SS+12 MIN)	ΔVX: -1.0 ΔVY: 0 ΔVZ: 0 ΔV REQ: -1.0	—	G&N AUTO	LIFT OFF	WT:36370.9 HP: HA:	RCS BURN
TEI	131:28:43 2 MIN 29 SEC	R:181.5 P:353.2 Y: 13.2	R:181.6 P: 57.6 Y: 13.2	DAYLIGHT (SR+8 MIN)	ΔVX: 3078.1 ΔVY: 708.2 ΔVZ: 39.0 ΔV REQ: 3158.7	2 Jet 14 Sec fps	G&N AUTO	LIFT OFF	WT:33626.6 HP: HA:	SPS BURN
MIDCOURSE CORRECTIONS MCC ₅ to MCC ₇	148:28 173:00 192:06	R: P: Y:	R: P: Y:	---	ΔVX: ΔVY: NOMINALLY ΔVZ: ZERO ΔV REQ:	—	G&N AUTO	PTC PTC ENTRY	—	TEI + 17 EI - 22 EI - 3

TABLE 1-2 LM BURN SCHEDULE

BURN/MANUEVR	GET1 BURN TIME ΔVc	ATTITUDE (DEG)		LIGHTING	ΔV (FPS)	ULLAGL ΔV (FPS)	TVC MOUL	REFSMAT	ΔV RESULT (SC ST, HP, HA)	REMARKS
		LH/LV	INERTIAL							
DOI	99:42:27 2 SEC 71.6	R: 0 P: 180 Y: 1.4	R: 0.1 P: 75.8 Y: 0	DARKNESS (SR - 2 MIN)	ΔVX: +57.4 ΔVY: -39.1 ΔVZ: -17.1 ΔV REQ: 71.6	2 Jet 7.5 Sec 1.5 fps	PGNCS AUTO	LOG SITE	WT: 33,696 HP: 8.73MM HA: 58.1 NM	DPS BURN
PD1	100:38:57 11MIN 53SEC 6747	R: 181.2 P: 171.7 Y: 0	R: 0 P: 104.2 Y: 0	DAYLIGHT	ΔVX: -4324 ΔVY: 3137 ΔVZ: 1365 ΔV REQ: 6747	2 Jet 7 1/2 Sec 1.5 fps	PGNCS AUTO	LOG SITE	WT: 16,624 HP: HA:	OPS BURN
ASCENT	122:28:11 434.6 SEC 6550	R: 0 P: 0 Y: 0	R: 0 P: 0 Y: 0	DAYLIGHT	ΔVX: ΔVY: ΔVZ: ΔV REQ:	---	PGNCS AUTO	LIFT OFF	WT: 5,094 AT INS HP: HA:	APS BURN
CSI	123:26:27 45.8 SEC 50.1	R: 0 P: 90 Y: 0	R: 0 P: 172 Y: 0	DARKNESS (SR - 4 MIN)	ΔVX: 50.1 ΔVY: 0.0 ΔVZ: 0.1 ΔV REQ: 50.1	---	PGNCS AUTO	LIFT OFF	WT: 5894.57 HP: 44.7 HA: 45.7	RCS + 2 2 JET BURN
PLANE CHANGE	123:55:25 0 0	R: - P: - Y: -	R: - P: - Y: -	DAYLIGHT (SR + 25 MIN)	ΔVX: 0 ΔVY: 0 ΔVZ: 0 ΔV REQ: 0	---	PGNCS AUTO	LIFT OFF	WT: 5895 HP: 44.7 HA: 45.7	RCS + Y 2 JET BURN
CDH	124:24:25 2.8 6.0	R: 0 P: 90 Y: 0	R: 0 P: 7.5 Y: 0	DAYLIGHT (SS - 15 MIN)	ΔVX: -0.2 ΔVY: 0.0 ΔVZ: 6.0 ΔV REQ: 6.0	---	PGNCS AUTO	LIFT OFF	WT: 5801 (11G) HP: 44.4 HA: 45.0	RCS - X 4 JET BURN
TPI	125:07:45 23.3 25.7	R: 0 P: 117.8 Y: 0	R: 0.1 P: 276 Y: 0.2	DARKNESS (MIDDLE OF DARKNESS)	ΔVX: 22.9 ΔVY: -0.1 ΔVZ: -11.5 ΔV REQ: 25.7	---	PGNCS AUTO	LIFT OFF	WT: 5857 HP: 43.8 HA: 62.6	RCS + 2 2 JET BURN
MCC ₁	125:17:46 0 0	R: - P: - Y: -	R: - P: - Y: -	DARKNESS (SR - 7 MIN)	ΔVX: 0 ΔVY: 0 ΔVZ: 0 ΔV REQ: 0	---	PGNCS AUTO	LIFT OFF	WT: 5840 HP: 43.6 HA: 62.6	RCS + 2 2 JET BURN NUMINALLY ZERO
MCC ₂	125:32:46 0 0	R: - P: - Y: -	R: - P: - Y: -	DAYLIGHT (SR + 8 MIN)	ΔVX: 0 ΔVY: 0 ΔVZ: 0 ΔV REQ: 0	---	PGNCS AUTO	LIFT OFF	WT: 5840 HP: 43.6 HA: 62.6	
1st BRAKING MNVR	125:42:22 0 0	R: - P: - Y: -	R: - P: - Y: -	DAYLIGHT (SR + 17 MIN)	ΔVX: 0 ΔVY: 0 ΔVZ: 0 ΔV REQ: 0	---	MANUAL	LIFT OFF	WT: 5840 HP: 44.0 HA: 62.3	RCS - 2 2 JET BURN
2nd BRAKING MNVR	125:44:03 9.6 SEC 10.6	R: 0.1 P: 210.4 Y: 259.9	R: 259.9 P: 118.3 Y: 0.1	DAYLIGHT (SR + 19 MIN)	ΔVX: ΔVY: ΔVZ: ΔV REQ: 10.6	---	MANUAL	LIFT OFF	WT: 5839 HP: 49.3 HA: 61.7	RCS - 2 2 JET BURN
3rd BRAKING MNVR	125:46:16 9.0 SEC 9.9	R: 0.1 P: 216.4 Y: 259.8	R: 259.8 P: 244.0 Y: 0.1	DAYLIGHT (SR + 20 MIN)	ΔVX: ΔVY: ΔVZ: ΔV REQ: 9.9	---	MANUAL	LIFT OFF	WT: 5832 HP: 54.1 HA: 61.2	RCS - 2 2 JET BURN
4th BRAKING MNVR	125:46:55 4.3 SEC 4.8	R: 0.1 P: 221.3 Y: 259.8	R: 259.8 P: 243.9 Y: 0.1	DAYLIGHT (SR + 22 MIN)	ΔVX: ΔVY: ΔVZ: ΔV REQ: 4.8	---	MANUAL	LIFT OFF	WT: 5825 HP: 56.6 HA: 61.0	RCS - 2 2 JET BURN
5th BRAKING MNVR	125:48:14 4.2 SEC 4.7	R: 0.1 P: 226.8 Y: 259.8	R: 259.9 P: 244.4 Y: 0.1	DAYLIGHT (SR + 23 MIN)	ΔVX: ΔVY: ΔVZ: ΔV REQ: 4.7	---	MANUAL	LIFT OFF	WT: 5822 HP: 59.1 HA: 60.9	RCS - 2 2 JET BURN

TABLE 1-3 LUNAR LANDING SITE DATA

DAY	SITE DESIG.	LAT.	LONG.	SUN ELEVATION ANGLES*	
				(72°L.AZ.)	(108°L.AZ.)
JULY 16	2(II P6)	0°43'N.	23°42'E.	10°	13°
JULY 18	3(II P8)	0°21'N.	1°18'W.	8°	11°
JULY 21	5(II P13)	1°42'N.	41°54'W.	6°	9°

*Sun elevation angles are for approximately 25 hours after LOI₁.

TABLE 1-4 LANDMARK TRACKING DATA
(JULY 16 LAUNCH)

SITE DESIG.	LAT.	LONG.	SUN EL.	GET
IP (F1)	1°17'N.	93°50'E.	69°	82:40
F1 (Pseudo)	1°40'N.	86°53'E.	62°	82:42
IP (130)	1°53'N.	28°42'E.	12°	96:48
LDMK 130 (LDG SITE 2)	1°16'N.	23°41'E.	7°	96:50

COPY
DATA

CSM FLIGHT PLAN NOTES

A. Crew

1. Crew designations are as follows:

<u>Designation</u>	<u>Prime</u>	<u>Backup</u>
Commander (CDR)	Armstrong	Lovell
Command Module Pilot (CMP)	Collins	Anders
Lunar Module Pilot (LMP)	Aldrin	Haise

2. Couch positions during the mission are as follows:

	<u>Left</u>	<u>Center</u>	<u>Right</u>
Launch	CDR	LMP	CMP
EPO	CDR	LMP	CMP
TLI	CDR	LMP	CMP
T&D	CMP	CDR	LMP
MCC's	CMP	CDR	LMP
LOI ₁ + LOI ₂	CMP	CDR	LMP
TEI	CMP	CDR	LMP
MCC's	CMP	CDR	LMP
ENTRY	CMP	CDR	LMP

3. All crewmen will sleep simultaneously during TLC and be awake during all major burns. The crew will follow a staggered sleep period during TEC.

Two crewmen will normally be in the sleep stations under the couches and one in the left couch. During the LOI Day sleep period, two crewmen will be in the couches because the probe and drogue will be stored in one of the sleep stations.

4. The crew will eat together when possible during meal periods (normally of 1-hour duration). Additional activities will be held to a minimum during meals.
5. PGA's will be worn during the following periods, but will not be "hard suited".

- (a) Launch - With helmet and gloves
 - (b) Earth Orbit - without helmet and gloves
 - (c) TLI - With helmet and gloves
 - (d) Undocking and docking - With helmet and gloves
- PGA's will not be worn for entry

6. During the mission, two crew status reports via air-to-ground communications will be made by the flight crew during each activity day. The first report will be given after the first meal of the day and will concern the sleep obtained during the previous sleep period. The second report will be given following the final meal of the day and will concern the radiation dose received during the previous 24 hours. The following information should be transmitted or logged as indicated:
- (a) A daily report of each crewman's best estimate as to sleep quantity and quality.
 - (b) A daily report of the integrated radiation dose each crewman receives.
 - (c) An onboard record of food and water consumption and exercise (no voice report required).
 - (d) Used fecal bags will be marked as to crewman and GET.
7. General flight plan updates containing changes to the scheduled next day's activities will be voiced up once a day.
8. Negative reporting will be used in reporting completion of each checklist.
9. No CSM biomedical switching is required. Continuous biomedical data are automatically transmitted to the ground simultaneously for all crewmen.

10. One crewman will wear headsets at all times during the mission.
11. All onboard gage readings will be read directly from the gages and will not be corrected by the appropriate calibration factors.
12. Periodic spacecraft systems monitoring is a continuing task and is not specifically scheduled in the flight plan timeline.

3. Maneuvers

1. CSM/LM and CSM attitude maneuvers will normally be at a rate of $0.2^{\circ}/\text{sec.}$ or $0.5^{\circ}/\text{sec.}$ unless other rates are required.
NOTE: At $0.2^{\circ}/\text{sec}$ 15 minutes is required to maneuver 180° . At $0.5^{\circ}/\text{sec.}$ 6 minutes is required to maneuver 180° .
2. Passive thermal control mode will be initiated before MCC_1 and maintained throughout the mission (except in lunar orbit) until at least three hours before entry except for interruptions for midcourse corrections, communications orientation (maximum interruption of three hours). PTC will not be initiated until approximately 7:00 GET.
3. In order to conserve SM RCS, the SPS engine will be used to "back-up" all LM rendezvous burns. The SPS gimbal motors will not be turned on during the "back-up" maneuver preparation. The CSM backup burn will be delayed 3 min. for the LM insertion burn only.
4. The first SPS burn will be on engine valves BANK "A" and the second burn will be on BANK "B".

C. Electrical Power System and Water Management

1. Spacecraft lift-off switch positions are listed in the Apollo Operations Handbook (Volume 2) for CSM 107.

2. The CSM will remain fully powered up throughout the mission (CMC, IMU and SCS in the "operate" configuration and optics power-up as required).
3. Fuel cell H₂ and O₂ purging is scheduled as follows: H₂ approximately every 24 hours and O₂ approximately every 48 hours.
4. Hydrogen VAC ION pumps will be inactive throughout the mission. The fuses will be pulled.
5. The O₂ VAC ION PUMP MAIN A/MAIN B CB (2) (Panel No. 229) will be open for launch but will be closed at 85% - 90% QTY (after pressure about VAC ION pump circuitry has decreased to vacuum and before pressure about the VAC ION pump increases significantly).
6. Potable water will be chlorinated once a day before each sleep period.
7. FC purges or waste water dumps will not be scheduled within one hour prior to optical sightings.
8. Waste H₂O dumping will be managed to allow:
 - (a) Maximum QTY:85-90%
 - (b) Minimum QTY:25%
 - (c) At LOI:QTY = 75%
 - (d) At CM-SM SEP:QTY = 90%
 - (e) No dumping after MCC until after LOI.
 - (f) Dumps will be performed (if required) within 2 hours preceding MCC maneuvers.
 - (g) In lunar orbit if dumping is required, dumps will be performed immediately prior to sleep periods
 - (h) The water dump will not be operated in the automatic mode at anytime during the mission.

9. The cryogenic heaters will be in AUTO during the mission and the fans will be operated manually. The fans will be cycled for one minute before and after each sleep cycle.
10. The batteries will be charged after TLI, LOI₂ and TEI. It is desirable to charge batteries during crew sleep period in order to get uninterrupted charge.

D. Environmental Control System and Cabin Pressurization

1. One CO₂ odor absorber filter (LiOH canister) is changed approximately every 12 hours or if CO₂ partial pressure is greater than 7.6mm Hg. There are 20 filters (2 in the canisters onboard and 18 stowed). The filter schedule is shown on Figure 1-4
2. An ECS redundant component check including the secondary evaporator operation, is performed at 24-hour intervals (in order to prevent secondary evaporator dry out), and prior to TLI, LOI (approximately 7 hours before), and entry (approximately 6 hours before). The secondary evaporator water control valves will be turned "OFF" after the check.
3. The evaporator operation will be as follows:
 - (a) Launch - primary loop operation
 - (b) Earth Orbit - primary loop operation and secondary loop test plus redundant operation test
 - (c) Post TLI - deactivate both evaporators
 - (d) LOI Minus 2 hours - activate primary evaporator
 - (e) Post TEI - deactivate primary evaporator
 - (f) Entry interface Minus 1.5 hours - activate primary evaporator
 - (g) Secondary evaporator may be activated (EI - 1 hour) at crew option for cold soak.

4. At lift-off the cabin will contain a 60% O₂/40% N₂ gas mixture. Cabin O₂ purge will be initiated after launch and will be terminated after TLI and prior to LM pressurization.
5. After the LM is pressurized (before ejection from the SIVB), the CSM maintains LM pressure by placing the LM/CM pressurization valve in the LM position (panel 12). This allows a maximum of 1.2 pounds per hour of O₂ flow into the LM. MCC-H will monitor O₂ usage and determine if excessive leak rates are being experienced by the combined CSM and LM.
6. The CM tunnel hatch will be installed during the docked lunar orbit sleep period and the probe and drogue will be stored in one of the sleep stations.
7. There is no CSM PTC mode required in lunar orbit, but a special attitude (see Communications Notes) will be maintained during the sleep period.

E. Guidance and Navigation

1. During lunar orbit, the CSM and LM will utilize the same landing site REFSMMAT such that the gimbal angles would be 0,0,0 at GET 100:50:50 (CSM) with the LM sitting face forward on landing site number two and the CSM over the landing site pitched up 90⁰ from local horizontal "heads up".
2. The IMU will be pulse-torqued to a PTC REFSMMAT Prior to setting up the PTC mode in order to avoid gimbal lock. Prior to a ΔV maneuver or midcourse navigation sightings, if yaw gimbal angle exceeds 60⁰, the IMU will be pulse-torqued back to the pad or landing site REFSMMAT and an IMU fine align (P52) will be performed. Pulse rate per axis is 1/2⁰/second. The accuracy for pulse-torquing the platform is 0.002 times the total angle.

3. The CMC will use the COLOSSUS 2A COMANCHE 51 flight program.
4. The CSM tracking light will be on continuously from undocking to landing and from LM lift-off to docking.

F. Procedures

1. Crew procedures called out in the flight plan may be found in the following documents:
 - (a) Apollo Operations Handbook - CSM-107 (AOH), Volume 2
 - (b) Apollo Operations Handbook - LM-5 (AOH), Volume 2
 - (c) Crew Checklist
 - (d) Rendezvous Procedure document
 - (e) Abort Summary document
 - (f) Reentry Procedures document
 - (g) Photography and TV Operations Plan
 - (h) Descent Procedures document
 - (i) Lunar Surface Operations Plan

G. Photography

1. There are requirements for photography and TV. These will be scheduled with other mission activities in the timeline (Section III).
2. Cameras and film are provided to photograph the following activities:
 - (a) Transposition/Docking
 - (b) Distance Earth Photography
 - (c) Long Distance Lunar Photography
 - (d) LM Undocking and Inspection
 - (e) LM Tracking During Descent
 - (f) Lunar Mapping Photography
 - (g) Crew Activities Evaluation
 - (h) Crew Observations
 - (i) LM Tracking During Ascent and Rendezvous

3. Landmark Tracking

The following assumption and data requirements were used in developing the landmark tracking procedures.

- (a) IMU to be realigned on the dark side preceding each tracking period.
- (b) MSFN coverage is reacquired after each tracking period. The tracking data will be acquired by MSFN after all the marks have been made and while N49 ($\Delta R, \Delta V$) is displayed. MSFN will give a GO when data acquisition has been verified.
- (c) The first mark will be taken with the spacecraft 30° to 40° above local horizontal. The time between marks should be a minimum of 25 seconds.
- (d) The pseudo landmark tracking will be used to determine the altitude of an area in which the LM will be making altitude checks after DOI. The data will be processed during the sleep period after the trackings and relayed to the LM prior to undocking.
- (e) The PRN range code will be transmitted and reacquired twice at AOS on the tracking revs to increase accuracy.

Table 1-4
LiOH CANISTER CHANGE SCHEDULE

CHANGE NUMBER	GET OF CHANGE	INTERVAL BETWEEN CHANGE (HRS:MIN)	ABSORBER USE TIME (CAN. NO.-HRS:MIN)
-	PRELAUNCH	-	-
1	10:30	12:00	*1 - 14:30
2	22:30	13:00	*2 - 26:30
3	35:30	12:30	3 - 25:00
4	48:00	11:00	4 - 25:30
5	59:00	11:30	5 - 23:30
6	71:30	12:30	6 - 22:30
7	84:00	12:00	7 - 24:00
8	96:00	13:30	8 - 24:30
9	109:30	11:30	9 - 25:30
10	121:00	12:00	10 - 25:00
11	133:00	12:00	11 - 23:30
12	145:00	11:30	12 - 24:00
13	156:30	11:30	13 - 23:30
14	168:00	12:00	14 - 23:00
15	180:00	11:00	15 - 23:30
16	191:00	-	16 - 23:00
17	-	-	17 - 15:00
18	-	-	18 - 04:00
			19 - NOT USED
			20 - NOT USED

* ASSUMES 4HR PRE LAUNCH USE

LUNAR MODULE FLIGHT PLAN NOTES

A. Crew

1. There will be two entries to the LM scheduled prior to LM activation and checkout. The first will be for crew familiarization scheduled at 56:00 GET, after MCC₃, and will be performed by the CDR and LMP in flight coveralls. The second IVT is scheduled at 81:30 GET, after LOI₂ and will be performed by the LMP in flight coveralls.
2. During the initial IVT (crew familiarization) the LM will not be powered up. To insure the switch settings as specified by the prelaunch configuration (LM-5 AOH Volume II) the Docking Hatch Switch will be secured "off".
3. The LMP will initiate the final LM activation and checkout in coveralls. The CDR will enter the LM in his PGA (without donning helmet and gloves). The LMP will return to the CM and don his PGA (without helmet and gloves). The LMP and CDR will don helmets and gloves and perform a PGA/ARS pressure integrity check just prior to the LM cabin regulator check.
4. The LM switch settings at the initial entry will be specified in the LM-5 AOH Volume II.
5. Two PLSS's and two OPS will be carried in the LM. The OPS's will be checked out prior to undocking during the housekeeping activities.
6. The CM transfer umbilical will not be used during LM activation and checkout.
7. The LM crew will be suited (without helmet and gloves) during the undocked portion of the mission. For undocking, staging, descent, ascent, and rendezvous the LM crew will be fully suited.

B. Guidance and Navigation

1. The LGC will use the LUMINARY-1A Revision 96 Flight Program.
2. The LM AGS will use Flight Program X.
3. Two LGC erasable memory dumps and MCC-H verifications will be accomplished prior to DOI. If a significant number of errors are found, memory correction and re-verification will be performed before DOI.
4. The LM IMU will be manually aligned to the CSM IMU during the DOI Day LM activation and checkout. P-52/AOT alignments will be performed as soon as possible prior to DOI.
5. All maneuvers during the undocked manned LM operations will be under PGNCs control.
6. The capability for MCC-H to update the LGC via uplink will normally be blocked by the LMP UP-DATA LINK switch (panel 12).
7. A LM COAS star sighting will be used during the DOI maneuver to check IMU drift rates. The star should remain within 2° of the initial COAS position during the maneuver. The AOT will not be used for this purpose. The lunar horizon will not be visible during the DOI maneuver.

C. RCS Operation and Interface Constraints

1. During CSM/LM docked checkout operations, the LM steerable and/or RR antennas will not be powered down once they have been activated.

The SM B3(-x) thruster will be deactivated before the LM steerable and/or RR antennas have been unstowed in order to prevent SM-RCS impingement on these antennas.

2. LM RCS "+x" two jet ullage (System B) will be used for unstaged ullage maneuvers in order to prevent asymmetrical RCS thrust caused by impingement on the descent stage.
3. The RCS interconnect will be used during the APS lift-off and ascent, but will not be used during the rendezvous maneuvers because of helium injection.

D. Passive Thermal Control Maneuvers

1. There is no requirement to perform any LM passive thermal control maneuvers during lunar orbit.
2. There will be no telemetry or crew monitoring of LM temperatures (or any other LM data) between LM pre-launch checkout and the post LOI-2 LM entry and inspection.

E. Rendezvous Radar

1. The turn-on and turn-off times for the rendezvous radar will be scheduled in such a manner as to prevent overheating of the rendezvous radar antenna.
2. Accurate RR range and range rate telemetry data will not be obtained on the lunar farside because a HBR TLM capability is not available between the LM and CSM for subsequent DSE dump after AOS. This situation prevents MSFN from analyzing the RR systems operation and LM RR LGC state vector update. Therefore, MSFN will check the accuracy of the update against ground

computation after AOS and update the LM state vector if required.

3. The RR shaft and trunion angles will be at zero during each AGS RR update.

F. Rendezvous

1. The LM tracking light will be on continuously between separation and touchdown and between launch and docking (except during PGNCS/AOT alignments). During PGNCS/AOT alignments (LM P52), the CSM will not be able to optically track the LM.

G. LM Pressurization

The LM cabin will contain N_2 and some ambient air at launch and will bleed down to zero pressure psi during the launch. The LM will be pressurized after transposition and docking and will remain pressurized until jettisoned.

H. LM Activation and Checkout Notes

The following activities will be performed during the periods as shown:

1. Post MCC₃

Perform general housekeeping chores
LM will not be powered up
Transfer equipment to LM (crew option)

2. Post LOI-2:

LM entry status check

Transfer from CSM to LM power for 10 minutes

Activate VHF-B LBR telemetry for 10 minutes

OPS check

Transfer all or remaining equipment to the LM

Perform general housekeeping chores

3. Docked Pre-DOI:

Verify CSM to LM roll calibration angle

LM entry status check

EPS activation - descent and ascent stage battery checkout

Inverter No. 2 checkout

Primary glycol loop activation

Caution and warning system checkout

Circuit breaker activation

Talkback system verification

ECS activation and checkout

Glycol pump checks (1, 2 and secondary)

VHF-B Simplex activation and C/O

VHF-A Simplex activation and C/O

Suit fan and water separation check

S-Band steerable antenna checks (TLM-HBR Mode 6.2)

PGNCS turn on and self test

S-Band secondary transceiver and amplifier checks (Mode 6.2)

LGC erasable memory dumps (two) and MSFN verification

LGC/CMC clock set and T-EPHEM update
LM docked-manual IMU alignment
AGS activation and self test
ARS/PGA pressure integrity checks
Cabin regulator checks
ORDEAL initialization
Rate gyro check
LGC DAP data load
Uplink the LM state vector, AGS "K" factor and REFSMMAT
DPS gimbal drive and throttle test
RCS Pressurization
RCS checkout (cold and hot fire)
AGS accelerometer and gyro calibration
DPS pressurization and checkout
Deploy landing gear
Update and align AGS to PGNCS
Unstow RR antenna and perform self test

4. Undocked Pre-DOI

LM inspection by CSM
Rendezvous radar tracking (P20)
VHF ranging operations
LM tracking light operation
IMU/AOT alignment
AGS initialization and update
Landing radar self test
AGS accelerometer and gyro calibration
Parallel ascent and descent stage batteries

5. DOI to Touchdown
 - Maneuver to PDI attitude
 - Mode II Rendezvous Radar lock - on
 - Update, align, and configure LM AGS's
 - MCC-H dump DSE
 - LM pitch over at P64
 - Manual attitude control to touchdown
 - CSM P20 auto maneuver for sextant track of the LM

6. Touchdown to Lift Off
 - Go/no go for 7 minutes
 - CSM P52 realign option 3 REFSMMAT
 - GO/no go for one CSM revolution
 - Simulated countdown
 - Calibrate AGS gyros
 - Ascent power - off
 - Initiate DPS venting
 - Load AGS ascent targeting
 - P57 gravity measure
 - AGS lunar align
 - P57 IMU realign, REFSMMAT option, 2, celestial body option, update RLS
 - P22 auto optics lunar optics
 - Align AGS to PGNCS
 - P27 update
 - P57 IMU realign T-align, gravity and one celestial body
 - PGNCS drift test
 - Go/no go for lunar stay
 - Initiate AGS
 - Align AGS to PGNCS
 - P22 orbital navigation
 - Select P12 ascent

End simulated countdown
AGS power down
P52 IMU realign option/preferred plan change REFSMMAT
Eat period (CSM & LM)
Rest period (CSM & LM)
SPS plane change
P52 IMU realign option 1 preferred
Landing site REFSMMAT
Systems preparation for egress
Preparation for egress
Pressure integrity check
Depressurize cabin, open hatch
EVA
Post EVA systems configuration
Rest period

7. Preparation for Lift Off

LGC self test
AGS turn on, self test & systems test
Turn on RR & self test
P57 IMU realign REFSMMAT gravity vector and celestial body
P22 lunar surface navigation
AGS lunar align
Eat period (CSM & LM)
DAP load
EPS, ED, ECS prestaging checks
APS pressurization and checkout
P57 IMU realign, T-align, gravity and initialize AGS SV
Enter P12
Prelaunch systems check
RR to operate
Align AGS to PGNCS
APS, lift-off

I. LM Procedures

Crew procedures called out in the flight plan may be found in the following documents:

- (a) Apollo Operations Handbook LM-5, Vol. 2
- (b) Crew Checklist
- (c) LM Rendezvous Procedures Document
- (d) LM Descent/Ascent Summary Document
- (e) Photography and TV Operations Plan

J. Photography

Cameras and film will be carried aboard the LM to photograph the following activities:

- (a) Record the movements of the astronauts during the LM egress on the lunar surface for crew integration studies in preparation for future missions.
- (b) Obtain photographs of the astronaut's environment relative to his ability to function on the lunar surface.
- (c) Obtain photographs of the LM and LM subsystems for engineering post flight analysis.
- (d) Obtain photographs of the lunar science experiments state after development to be used for data reduction and post flight analysis of the findings.
- (e) Obtain photographs of the moon and its environment for subsequent scientific analysis.

COMMUNICATIONS PLAN

General mission notes and mission phase operational philosophies are presented in this section. The communications considerations include voice, data, ranging and recording by both spacecraft.

A basic communications switch configuration for both spacecraft is presented. Variations from the basic communications required during the mission phases are identified under the appropriate mission phase.

A. General Notes

1. All voice communications, CSM and LM HBR data transmissions at lunar distance will normally require the use of the high gain or steerable antennas with 85-ft. and 30-ft. "cooled" MSFN antennas.
2. During communications, the spacecraft will be referred to by name (Apollo 11) and MCC-H will be referred to as Houston. Code names may be assigned to the CSM and LM for undocked operations.
3. The timeline will show when the CAP-COMM should send voice data simultaneously to the CSM and LM. Only one MCC-H CAP-COMM will normally be used for all CSM and LM communications.
4. It is desirable that LM/CSM be configured to HBR during any MSFN uplinks so that MSFN can verify data was received by the spacecraft.
5. The preferred inflight S-Band communications mode for CSM and LM are:
 - (a) Uplink Mode 6 (Voice, PRN and Udata)
 - (b) Downlink Mode 2 (Voice, PRN, TLM-HBR)

6. A basic communications switch configuration for the LM and CSM is as follows:

CSM

Audio panel (3)

MODE (3) - INTERCOM/PTT
S BD (3) - T/R
SUIT PWR (3) - on (up)
AUDIO CONT (3) - NORM
PWR (3) - AUDIO/TONE
VHF AM (3) - T/R
INTERCOM (3) - T/R
PAD COMM (3) - OFF

S-band normal

S BD XPNDR - PRIM
S BD PWR AMPL PRIM - PRIM
S BD PWR AMPL HI - HI
S BD MODE VOICE - VOICE
S BD MODE PCM - PCM
S BD MODE RNG - RNG

VHF AM

VHF AM A - OFF
VHF AM B - off (ctr)
VHF AM RCV - off (ctr)

VHF BCN - OFF

VHF RNG - OFF

TAPE recorder

TAPE RCDR PCM - PCM/ANLG
TAPE RCDR RCD - RCD
TAPE RCDR FWD - FWD

S band aux

S BD AUX TAPE - off (ctr)
S BD AUX TV - off (ctr)

Up TLM

UP TLM DATA - DATA
UP TLM CMD - NORM
PWR AMPL tb - gray
(indicates pwr to amplifier)
TAPE MOTION tb - gray
(indicates tape motion)

S Band Antenna

S BD ANT OMNI A - A
S BD ANT OMNI - OMNI

Power

SCE - NORM
PMP - NORM

TLM inputs

PCM BIT RATE - LO
VHF ANT - SM LEFT
RNDZ XPNDR - OFF (PNL 100)
RNDZ XPNDR - OPR (PNL 101)
S BD SQLCH - OFF
UP TLM - BLOCK (MDC-2)
UP TLM - ACCEPT (PNL 122)

LM

CB/AC BUS B = S BD ANT - close

CB/AC BUS A: TAPE RCDR - close

CB COMM:

UP DATA LINK - close

COMM: UPLINK SQUELCH sw - ENABLE

UP DATA LINK sw - OFF

SEC S BD XMTR/RCVR - close

SEC S BD PWR/AMPL - close

VHF B XMTR - close

VHF A RCVR - close

CDR AUDIO - close

AUDIO: (CDR)

S-BAND T/R sw - S BAND T/R

ICS T/R sw - ICS T/R

RELAY ON sw - RELAY OFF

MODE sw - ICS/PTT

AUDIO CONT sw - NORM

VHF A sw - T/R

VHF B sw - OFF

CB COMM:

DISP - close

SE AUDIO - close

VHF A XMTR - close

VHF B RCVR - close

PRIM S BD PWR AMPL - close

PRIM S BD XMTR/RCVR - close

S BD ANT - close

PMP - close

TV - open

CB HTR: S BD ANT - close

CB CAMR: SEQ - open

AUDIO: (LMP)

S BAND T/R sw - S BAND T/R

ICS T/R sw - ICS T/R

RELAY ON sw - RELAY OFF

MODE sw - ICS/PTT

AUDIO CONT sw - NORM

VHF A sw - T/R

VHF B sw - OFF

COMM:

S BAND MODULATE sw - PM

S BAND XMTR/RCVR sw - PRIM

S BAND PWR AMPL sw - PRIM

S BAND VOICE sw - VOICE

S BAND PCM sw - PCM

S BAND RANGE sw - RANGE

VHF A XMTR sw - VOICE

VHF A RCVR sw - ON

VHF B XMTR sw - DATA

VHF B RCVR sw - OFF

TLM BIOMED sw - as required

TLM PCM sw - HI

RECORD sw - OFF

COMM ANT:

VHF ANTENNA - FWD/AFT

TRACK MODE sw - AUTO

S-Band sel - SLEW

7. MSFN will not switch CSM or LM antennas - this will be a crew action (except during sleep - if required).
8. CSM recording of LM VHF B LBR TM is not possible during periods when VHF ranging between the vehicles is taking place.
9. CSM S-Band backup communication modes checks will not be made. The LM communication system will be used as a backup communication system.
10. CSM FM modes are used for DSE playbacks, TV and backup TM. The high gain antenna will be required for FM operations after TLI.
11. CSM-TV can be scheduled in real time if the Goldstone 85-ft. antenna is in view of the spacecraft. CSM-TV via the Madrid 85-ft. antenna should be scheduled approximately 15 hours in advance in order to reserve communications satellite time.
12. The CM communications system switches will be configured to permit MCC-H real time control of routine communications switching and maximum crew control of the communications without the crew having to use CMD RESET.
13. The CSM updata link will normally be blocked by the crew Up TLM ACCEPT/BLOCK switch on MDC 2. This will not prevent MCC-H from using real time comm and from controlling the communication system.
14. The S-Band "squelch" will be on during the simultaneous sleep period in order to prevent MSFN fade-out noise from disturbing the crew.

15. LM voice recorder has a maximum utilization of 10 hours. This recorder will be used during LM operations to record all LM voice data during undocked operations (27 hours 42 minutes). The recorder will be operated in the VOX mode.
16. A small portable voice recorder will be carried in the CM to be used at the discretion of the crew as a voice recorder backup. This recorder will not be transferred to the LM for use during undocked operations.
17. LM AGS initialization requires HBR because the AGS uses the PGNCSTLM downlink state vector and times as the data source.
18. CSM DSE will be operated as follows:
 - . The DSE will normally be operated via ground command except for special cases where the operation is time limited. In these cases the crew may be asked (either by voice or flight plan update) to rewind the tape.
 - . DSE will be operated HBR during the launch phase. These data will be dumped if real time launch data are lost.
 - . During the earth orbit period when the CSM is not over a MSFN station, CSM TLM-LBR data will be recorded on the DSE and will be dumped during the pass over the US and over CRO prior to TLI, if possible.
 - . DSE will be used for CSM HBR and voice recording during all CSM engine burns.
 - . DSE data and voice recordings will be made in CSM LBR mode whenever possible in order to minimize the DSE dump time.

- . All critical data will be hand recorded by the crew when not in voice contact with MSFN if at all possible. DSE voice recording will be used as backup for recording critical data.
- . During translunar PTC simultaneous sleep periods using the HGA REACQ communications mode the DSE will be used to record LBR data when the HGA is not in the MSFN field of view.
- . During lunar orbit LM operations, the DSE will be used to record LM-TLM-LBR data during all LM phases/events that occur on the lunar farside (unless VHF ranging is required).
- . During lunar orbit, time (in the attitude hold control mode) will be provided in the flight timeline to allow for MCC-H DSE dump, rewind and start of DSE after each MSFN AOS (acquisition of signal) except where a DSE dump would interfere with DSE recording of critical CSM backup TLM data or the HGA is not visible to MSFN.
- . Twenty-five minutes will normally be allowed for the complete data dump cycle for CSM and LM LBR data recorded on the lunar farside. HBR data will require additional dump time depending on the length of the recording.
- . DSE will be used to record all HBR entry data during the black-out region.

B. Launch - Earth Orbit Phase

1. OMNI B and VHF LEFT will be selected for launch. OMNI D will be selected by the crew during boost phase if the launch azimuth is less than 96° or OMNI C if the launch azimuth is greater than 96° . OMNI D will probably be the best antenna for earth orbit.
2. VHF Duplex B will be used for launch, and Simplex A for earth orbit operations.
3. VHF Simplex A will be used for entry to be compatible with recovery forces communications.

C. Translunar and Transearth Coast Phase

1. The translunar and transearth sleep communications mode will be as follows: The CSM x-axis will be placed normal to the ecliptic plane. The CSM will be placed in GNCS $+20^\circ$ pitch and yaw attitude hold. All four SM RCS quads will be used. The CSM will be rolled at a rate of approximately one revolution per hour. During the near earth sleep periods prior to 30 hours GET (range less than 120Knm) omni antennas B and D can be used. During the other sleep periods (beyond 120Knm) the high gain antenna can be used in the REACQ mode (panel 2). The REACQ configuration will provide approximately 210 degrees of HGA coverage per CSM/LM revolution or 35 minutes of MSFN coverage per hour, (for a CSM spin rate of one revolution per hour). The REACQ configuration will also allow MCC-H to use real time control to select TLM HBR or LBR and to dump the DSE during each spacecraft revolution. The REACQ sleep mode will be checked before the second translunar coast sleep period.

2. During translunar and transearth coast PTC mode crew awake periods, the crew will use manual antenna switching to maintain continuous communications with MSFN via OMNI and/or HGA. If OMNI's are used the S-Band squelch will be disabled to allow the crew to use the upvoice discriminator noise as a cue to indicate when to switch to another OMNI.
3. All CSM communications checkouts may be performed during translunar coast (post TD&E to pre-LOI), however, the lunar sleep comm mode will be checked during lunar orbit prior to sleep.

D. Lunar Orbit Phase

1. During CSM/LM lunar orbit, docked, crew awake, coasting flight operations, one standard attitude (referenced to the landing site REFSMMAT) will be used in order to allow MSFN to acquire either the CSM HGA or LM steerable antenna without crew assistance.
2. After each AOS in lunar orbit, MSFN will send the PRN range code to acquire and lock-on the spacecraft for ranging determination. Upon acquisition the Clock Doppler System is also utilized for incremental ranging determination. The time required for PRN lock-on and ranging is approximately 6 minutes and is a continuous operation until LOS.
3. During lunar orbit, the CSM and LM S-Bands will remain operational on the lunar farside.
4. The LM steerable antenna and the CSM HGA will not be in view of MSFN during CSM tracking of the landing site while docked. The CSM HGA will not be in view of MSFN when undocked during CSM tracking. To allow communications with MSFN, the CSM and LM omni antennas and LBR are selected.

5. VHF Ranging/Data switching will be performed along with CSM sextant tracking of the LM. Voice silence between vehicles should be maintained for approximately 10 seconds while acquiring VHF ranging.
6. VHF A Simplex is normally used for all VHF Voice Communications except during VHF ranging when VHF B Duplex is being used.
7. At LOS the CSM crew will initiate Up TLM CMD RESET then NORMAL if DSE motion is not noted. This indicates that MSFN lost contact prior to reconfiguring DSE after a dump.
8. The communications mode for the lunar orbit sleep period will be as follows:
The CSM will be referenced to landing site number two and will be in an attitude which will place two RCS quads toward the sun and two RCS quads toward the lunar surface. The SPS engine will be pointed toward the earth, and the spacecraft pitched to allow the HGA to acquire MSFN without interference from the SPS engine bell. The HGA will be in the REACQ mode and S-Band squelch will be enabled. The S-Band system will be controlled by RTC at MCC-H and will be in TLM-HBR on the lunar earthside and LBR/DSE recording on the lunar farside. This procedure will provide approximately 75 minutes of HBR for each lunar orbit and will permit MCC-H real time control of the DSE and playback of LBR data recorded on the lunar farside. This communication mode will be checked for suitability just prior to the lunar orbit sleep period.
9. In lunar orbit, MSFN will acquire the CSM high gain antenna/LM steerable antenna for each AOS unless specified differently in the flight plan timeline.
10. LM TLM will be switched to LBR at each LOS and to HBR at AOS by the LMP unless specified otherwise in the flight plan timeline.

11. LM Bio-Med switching will be checked out in lunar orbit and will begin when the CDR enters the LM for activation and checkout (approximately 94:50 GET). The LMP will switch the Bio-Med telemetry from the CDR to the LMP at a convenient time in the flight plan (approximately 99:10 GET). The crewman will be monitored continuously beginning with LM ingress and lunar stay, through docking and LM egress. While both crewmen are in the LM the LMP will manually switch the Bio-Med monitor system every two hours except during the sleep period. During EVA the crewman will be monitored simultaneously through the Extra Vehicular Communications Systems (EVCS) relayed to MCC-H via LM S-Band telemetry.

E. Lunar Exploration Phase

1. Normal CSM communications between MSFN/LM will be by S-Band during the lunar exploration period.
2. If additional communications capability is required the S-Band erectable antenna will be deployed by the EVA crewman and will be utilized for all LM/MSFN/CSM communications.
3. During periods when both crewmen are EVA, the "AR" position (Relay Mode) will be the normal communication mode on each of the Extravehicular Communication System (EVCS). The CDR will relay the LMP VHF voice and Data to the LM which in turn will relay to MCC-H via S-Band.
4. When both crewmen are EVA, the LM will be configured to the basic communications except for the following:
 - S BAND MODULATE sw - FM
 - VHF ANTENNA - EVA
 - S BAND sel - LUNAR STAY
 - AUDIO: MODE sw - VOX (both)
 - AUDIO: RELAY ON sw - RELAY ON (LMP)

SECTION II - UPDATE FORMS

MANEUVER UPDATE FORMS

This section contains samples of the update pads which are contained in the In Flight Data File onboard the spacecraft. The CSM forms are as follows:

1. TLI Maneuver
2. P37 Block Data
3. P27 Update
4. P30 Maneuver (External ΔV)
5. Entry
6. Earth Orbit Entry Update
7. Earth Orbit Block Data
8. CSM SEP Pad
9. CSM Rescue One
10. DOI P76 Pad
11. CSI
12. CDH
13. TPI

The LM forms are:

1. P30 LM Maneuver (External ΔV)
2. P27 Update
3. P76 Update
4. P32 CSI Update
5. P33 CDH Update
6. P34 TPI Update
7. AGS State Vector Update
8. PDI Pad
9. Lunar Interface Pad
10. LM Ascent Pad

APRIL 1, 1969	TLI	TLI										TLI
		X	•	•		X	•	•				
	X	X	X		X	X	X				R	TLI
	X	X	X		X	X	X				P	
	X	X	X		X	X	X				Y	
	X	X	X	•	X	X	X	•			BT	
				•				•			$\Delta VC'$	
	+				+						VI	
	X	X	X		X	X	X				R	SEP
	X	X	X		X	X	X				P	
	X	X	X		X	X	X				Y	
	X	X	X		X	X	X				R	EXTRACTION
	X	X	X		X	X	X				P	
	X	X	X		X	X	X				Y	
	TLI 10 MIN ABORT P = _ _ _											

TLI PAD

TB 6p	X:XX:XX (HRS:MIN:SEC)	PREDICTED TIME OF BEGINNING OF S-IVB RESTART PREPARATION FOR TLI (TB6 = TLI IGN -9 MIN)
R	XXX (DEG)	PREDICTED SPACECRAFT IMU
P	XXX (DEG)	GIMBAL ANGLES AT TLI
Y	XXX (DEG)	IGNITION
BT	XX:XX (MIN:SEC)	DURATION OF TLI BURN
Δ VC'	XXXXX.X (fps)	NOMINAL TLI Δ V SET INTO EMS Δ V CONTROL
VI	+XXXXX fps)	NOMINAL INERTIAL VELOCITY DISPLAYED ON DSKY AT TLI CUTOFF
R SEP	XXX (DEG)	PREDICTED SPACECRAFT IMU
P SEP	XXX (DEG)	GIMBAL ANGLES AT COMPLETION
Y SEP	XXX (DEG)	OF S-IVB MNVR TO CSM/S-IVB SEP ATTITUDE
TLI 10 MIN ABORT P		PITCH ANGLE TO PERFORM TLI ABORT MANEUVER

P37 BLOCK DATA

GETI	XXX:XX	TIME OF IGNITION (HR. MIN.)
Δ VT	XXXX (FPS)	DELTA V REQUIRED AT GETI.
LONG	\pm XXX (DEG)	LONGITUDE OF LAND- ING SITE
GET _{400K}	XXX:XX	TIME OF ENTRY INTERFACE

		P27 UPDATE													
PURP		V				V				V					
GET		:				:				:					
P27	304 01	INDEX				INDEX				INDEX				P27	
	02														
	03														
	04														
	05														
	06														
	07														
	10														
	11														
	12														
	13														
	14														
	15														
	16														
	17														
	20														
	21														
	22														
	23														
	24														
	APRIL 1, 1969	N34	HRS	X	X	X					X	X	X		
			MIN	X	X	X	X				X	X	X	X	
		NAV	CHECK SEC	X	X						X	X			
		N43	LAT		0							0			
	LONG														
	ALT	+	0						+	0					

P27 UPDATE

PURP	XXX	TYPE OF DATA TO BE RECEIVED (SUCH AS: NAV - LIFT-OFF TIME)
V	XX	TYPE OF COMMAND LOAD (70 - 71 - 72 - 73)
GET	XXX:XX:XX(HR:MIN:SEC)	TIME DATA RECORDED
01	XX (OCTAL)	INDEX NO. OF COMMAND WORDS IN LOAD
02-24	XXXXX	NO. OF CORRECTION COMMAND WORDS
NAV CHECK		TO CONFIRM POINT ABOVE GROUND TRACK FOR A GIVEN TIME
T	XX:XX:XX(HRS:MIN:SEC)	TIME
LAT	XX:XX (DEG)	LATITUDE
LONG	XXX:XX (DEG)	LONGITUDE
ALT	XXX.X (nm)	ALTITUDE

		P30 MANEUVER						
P30	SET STARS						PURPOSE	
							PROP/GUID	
							WT	N47
		R ALIGN _____	0	0		•	P TRIM	N48
		P ALIGN _____	0	0		•	Y TRIM	
		Y ALIGN _____	+	0	0		HRS	GET1
			+	0	0	0	MIN	N33
			+	0			SEC	
		ULLAGE _____				•	ΔV_X	N81
		_____				•	ΔV_Y	
_____				•	ΔV_Z			
		X	X	X		R		
		X	X	X		P		
		X	X	X		Y		
		+			•	H _A	N44	
					•	H _P		
		+			•	ΔVT		
HORIZON/WINDOW _____	X	X	X	•	•	BT		
_____	X				•	ΔVC		
_____	X	X	X	X		SXTS		
_____	+			•	0	SFT		
_____	+			•	0	0	TRN	
		X	X	X		BSS		
		X	X			SPA		
		X	X	X		SXP		
OTHER _____		0			•	LAT	N61	
_____					•	LONG		
_____	+				•	RTGO	EMS	
	+					VIO		
			•	•		GET	0.05G	

P30 MANEUVER

PURPOSE	XXXXXX	TYPE OF MNVR TO BE PERFORMED
PROP/GUID		PROPULSION SYSTEM (SPS/RCS)/ GUIDANCE (SCS/G&N)
WT	XXXXX (lbs)	PREMANEUVER VEHICLE WEIGHT
P TRIM	X.XX (DEG)	SPS PITCH GIMBAL OFFSET TO PLACE THRUST THROUGH THE CG
Y TRIM	X.XX (DEG)	SPS YAW GIMBAL OFFSET TO PLACE THRUST THROUGH THE CG
GETI	XX:XX:XX (HRS:MIN:SEC)	TIME OF MNVR IGNITION
ΔV_X	XXXX.X (fps)	P30 VELOCITY TO BE GAINED COMPONENTS IN LOCAL VERTICAL COORDINATES
ΔV_Y	XXXX.X (fps)	
ΔV_Z	XXXX.X (fps)	
R	XXX (DEG)	IMU GIMBAL ANGLES OF MANEUVER ATTITUDE
P	XXX (DEG)	
Y	XXX (DEG)	
H_A	XXXX.X (nm)	PREDICTED APOGEE ALTITUDE AFTER MANEUVER
H_P	XXXX.X (nm)	PREDICTED PERIGEE ALTITUDE AFTER MANEUVER
ΔVT	XXXX.X	TOTAL VELOCITY OF MANEUVER
BT	X:XX (MIN:SEC)	MANEUVER DURATION
ΔVC	XXXX.X (fps)	PREMANEUVER ΔV SETTING IN EMS ΔV COUNTER
SXTS	XX (OCTAL)	SEXTANT STAR FOR MANEUVER ATTITUDE CK
SFT	XXX.X (DEG)	SEXTANT SHAFT SETTING FOR MANEUVER ATTITUDE CK
TRN	XX.X (DEG)	SEXTANT TRUNNION SETTING FOR MANEUVER ATTITUDE CK
BSS	XXX (OCTAL)	BORESIGHT STAR FOR MANEUVER ATTITUDE CK USING THE COAS
SPA	XX.X (DEG)	BSS PITCH ANGLE ON COAS

MANEUVER PAD (cont'd)

SXP	X.X (DEG)	BSS X POSITION ON COAS
LAT LONG	XX.XX XXX.XX	LATITUDE AND LONGITUDE OF THE LANDING POINT FOR ENTRY GUIDANCE
RTGO	XXXX.X	RANGE TO GO FOR EMS INITIALIZATION
VIO	XXXXXX (fps)	INERTIAL VELOCITY AT .05G FOR EMS INITIALIZATION
GET(.05G)	XX:XX:XX	TIME OF .05G
SET STARS		STARS FOR TELESCOPE FOR BACKUP GDC ALIGN
R, P, Y (ALIGN)		ATTITUDE TO BE SET IN ATTITUDE SET TW FOR BACKUP GDC ALIGN
ULLAGE		NO. OF SM RCS JETS USED AND LENGTH OF TIME OF USAGE
HORIZON WINDOW		WINDOW MARKING AT WHICH HORIZON IS PLACED AT A SPECIFIED TIG (ATT CK)
OTHER		ADDITIONAL REMARKS VOICE UP BY MCC-H

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		ENTRY																
		X	X	X												AREA		
		X	X	X												R	0.05 G	
		X	X	X												P	0.05G	
		X	X	X												Y	0.05G	
																	GET	HOR
		X	X	X													P	CK EI-17
			0														LAT	N61
																	LONG	
		X	X	X													MAX	G
		+															V _{400K}	N60
		-	0	0													γ _{400K}	
		+															RTGO	EMS
+															V10			
															RRT			
LUNAR ENTRY		X	X													RET	0.05G	
		+	0	0												D _L MAX	N69	
		+	0	0												D _L MIN		
		+														V _L MAX		
		+														V _L MIN		
		X	X	X													D _O	
		X	X														RET	V _{CIRC}
		X	X														RETBBO	
		X	X														RETEBO	
		X	X														RETDRO	
		X	X	X	X												SXTS	
		+													0		SFT	EI-2
+													0	0	TRN			
APRIL 1, 1969		X	X	X												BSS		
		X	X													SPA	EI-2	
		X	X	X												SXP		
		X	X	X	X											LIFT VECTOR		

ENTRY PAD

AREA	XXX	SPLASHDOWN AREA DEFINED BY TARGET LINE
R .05G	XXX(DEG)	SPACECRAFT IMU GIMBAL ANGLES
P .05G	XXX(DEG)	REQUIRED FOR AERODYNAMIC
Y .05G	XXX(DEG)	TRIM AT .05G
GET (HOR CK)	XX:XX:XX (HRS:MIN:SEC)	TIME OF ENTRY ATTITUDE HORIZ CHECK AT EI -17 MIN.
P (HOR CK)	XXX(DEG)	PITCH ATTITUDE FOR HORIZON CHECK AT EI -17 MIN
LAT	+XX.XX(DEG)	LATITUDE OF TARGET POINT
LONG	+XXX.XX(DEG)	LONGITUDE OF TARGET POINT
MAX G	XX.X (G's)	PREDICTED MAXIMUM REENTRY ACCELERATION
V _{400K}	XXXXX (fps)	INERTIAL VELOCITY AT ENTRY INTERFACE
γ _{400K}	X.XX(DEG)	INERTIAL FLIGHT PATH ANGLE AT ENTRY INTERFACE
RTGO	+XXXX.X(nm)	RANGE TO GO FROM .05G TO TARGET FOR EMS INITIALIZATION
VIO	+XXXXX.(fps)	INERTIAL VELOCITY AT .05G FOR EMS INITIALIZATION
RRT	XX:XX:XX (HRS:MIN:SEC)	REENTRY REFERENCE TIME BASED ON GET OF PREDICTED 400K (DET START)
RET .05G	XX:XX (MIN:SEC)	TIME OF .05G FROM 400K (RRT)
D _L MAX	X.XX (G's)	MAXIMUM ACCEPTABLE VALUE OF PREDICTED DRAG LEVEL (FROM CMC)
D _L MIN	X.XX (G's)	MINIMUM ACCEPTABLE VALUE OF PREDICTED DRAG LEVEL (FROM CMC)
V _L MAX	XXXXX (fps)	MAXIMUM ACCEPTABLE VALUE OF EXIT VELOCITY (FROM CMC)
V _L MIN	XXXXX (fps)	MINIMUM ACCEPTABLE VALUE OF EXIT VELOCITY (FROM CMC)

ENTRY PAD (cont'd)

DO	X.XX (G's)	PLANNED DRAG LEVEL DURING CONSTANT G
RET V _{CIRC}	XX:XX (MIN:SEC)	TIME FROM EI THAT S/C VELOCITY BECOMES CIRCULAR
RETBBO	XX:XX (MIN:SEC)	TIME FROM EI TO THE BEGINNING OF BLACKOUT
RETEBO	XX:XX (MIN:SEC)	TIME FROM EI TO THE END OF BLACKOUT
RETDRO	XX:XX (MIN:SEC)	TIME FROM EI TO DROGUE DEPLOY
SXTS	XX(OCTAL)	SEXTANT STAR FOR ENTRY ATTITUDE CHECK
SFT	XXX.X(DEG)	SEXTANT SHAFT SETTING FOR ENTRY ATTITUDE CHECK
TRN	XX.X(DEG)	SEXTANT TRUNNION SETTING FOR ENTRY ATTITUDE CHECK
BSS	XXX(OCTAL)	BORESIGHT STAR FOR ENTRY ATTITUDE CHECK USING THE COAS
SPA	XX.X(DEG)	BSS PITCH ANGLE ON COAS
SXP	X.X(DEG)	BSS X POSITION ON COAS
LIFT VECTOR	XX	LIFT VECTOR DESIRED AT .05G's BASED ON ENTRY CORRIDOR

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		EARTH ORBIT ENTRY UPDATE													
		X				-			X					-	
APRIL 1, 1969		X	X	-				X	X	-				ΔV TO	
		X	X	X				X	X	X				R 0.05G EMS	
		X	X	X				X	X	X				P 0.05G	
		X	X	X				X	X	X				Y 0.05G	
		+						+						RTGO EMS	
		+						+						V10	
		X	X			•		X	X			•		RET 0.05G	
			0			•			0			•		LAT N61	
						•						•		LONG	
		X	X			•		X	X			•		RET 0.2G	
						•						•		DRE (55°) N66	
		R	R			/		R	R			/		BANK AN	
		X	X			•		X	X			•		RET RB	
		X	X			•		X	X			•		RETBBO	
		X	X			•		X	X			•		RETEBO	
X	X			•		X	X			•		RETDROG			
X	X	X				X	X	X				(90°/fps) CHART			
X	X					X	X					DRE (90°) UPDATE			
POST BURN															
X	X	X				X	X	X					P 0.05G		
+						+						•	RTGO EMS		
+						+							V10		
X	X			•		X	X			•			RET 0.05G		
E.O. ENTRY		X	X			•		X	X			•		RET 0.2G	
						•						•		DRE ±100 nm N66	
		R	R			/		R	R			/		BANK AN	
		X	X			•		X	X			•		RETRB	
		X	X			•		X	X			•		RETBBO	
		X	X			•		X	X			•		RETEBO + 46 SEC	
X	X			•		X	X			•		RETDROG TO MAIN			
														E.O. ENTRY	

ENTRY UPDATE AND POSTBURN UPDATE

AREA	XXX-X	RECOVERY AREA FIRST 3 DIGITS - LANDING REVOLUTION LAST DIGIT - RECOVERY AREA AND SUPPORT CAPABILITIES
ΔV TO		
R,P,Y .05G	XXX (DEG)	
RTGO	XXXX.X (nm)	RANGE TO GO FROM .05G TO TARGET
VIO	XXXXX. (fps)	INERTIAL VELOCITY AT .05G
RET	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO .05G
LAT	+XX.XX (DEG)	LATITUDE OF LANDING TARGET POINT
LONG	+XXX.XX (DEG)	LONGITUDE OF LANDING TARGET POINT
RET .2G	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO .2G
DRE	+XXXXX. (nm)	DOWNRANGE ERROR AT .2G
BANK AN	XX/XX (DEG/DEG)	BACKUP BANK ANGLE FOR SCS ENTRY: ROLL RIGHT/ROLL LEFT
RETRB	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO REVERSE BACKUP BANK ANGLE
RETBBO	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO BEGINNING OF COMMUNICATIONS BLACKOUT
RETEBO	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO END OF COMMUNICATIONS BLACKOUT
RETDROG	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO DROGUE CHUTE DEPLOYMENT

ENTRY UPDATE AND POSTBURN UPDATE (Cont'd)

CHART UPDATE

90 ⁰ /fps	+XX	VALUES USED TO RE-PLOT BACKUP ENTRY CHART - ΔV AND DOWN RANGE ERROR @ 90 ⁰ BANK ANGLE
DRE (90 ⁰)		

POST BURN

P 0.05G	xxx (DEG)	PITCH ANGLE @ ENTRY INTERFACE
RTGO	+XXXX.X (NM)	RANGE TO GO FROM .0.05G TO TARGET FOR EMS COUNTER
VIO	+XXXXX (fps)	INERTIAL VELOCITY @ 0.05G
RET 0.05G	XX:XX(NM:SEC)	TIME FROM RETROFIRE TO 0.05G
RET 0.2G	XX:XX(MIN:SEC)	TIME FROM RETROFIRE TO 0.2G
DRE	⁺ -XXXX.X(NM)	DOWN RANGE ERROR (+ OVERTHOOT)
BANK AN	XX/XX (DEG/DEG)	BACKUP BANK ANGLE FOR SCS ENGRY: ROLL RIGHT/ROLL LEFT
RETRB	XX:XX(MIN:SEC)	TIME FROM RETROFIRE TO REVERSE BACK UP ANGLE
RETBBO	XX:XX (MIN:SEC)	TIME FROM RETROFIRE TO BEGINNING OF COMMUNICATIONS BLACKOUT
RETEBO	XX:XX (NM=SEC)	TIME FROM RETROFIRE TO END OF COMMUNICATIONS BLACKOUT
RETDROG	XX=XX	TIME FROM RETROFIRE TO DROGUE CHUTE DEPLOYMENT

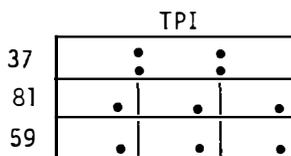
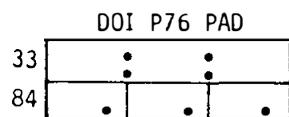
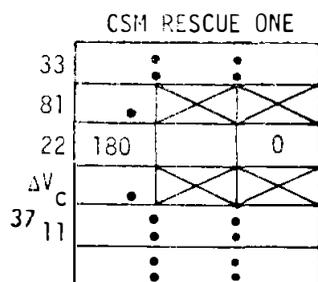
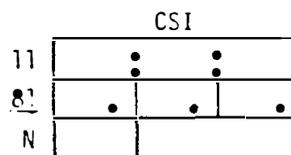
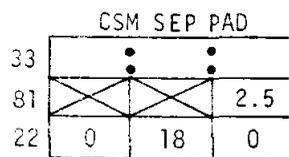
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		EARTH ORBIT BLOCK DATA																
APRIL 1, 1969	E.O. BLOCK	X	X							X	X						AREA	E.O. BLOCK
		X	X	X						X	X	X					LAT	
		X	X							X	X						LONG	
																	GETI	
		X	X	X						X	X	X					ΔV_C	
		X	X							X	X						AREA	
		X	X	X						X	X	X					LAT	
		X	X							X	X						LONG	
																	GETI	
		X	X	X						X	X	X					ΔV_C	
		X	X							X	X						AREA	
		X	X	X						X	X	X					LAT	
		X	X							X	X						LONG	
																	GETI	
		X	X	X						X	X	X					ΔV_C	
E.O. BLOCK	E.O. BLOCK	X	X													AREA		
		X	X	X						X	X	X				LAT		
		X	X							X	X					LONG		
																GETI		
		X	X	X						X	X	X					ΔV_C	
REMARKS:																		

EARTH ORBIT BLOCK DATA

AREA	XXX-X	RECOVERY AREA FIRST THREE DIGITS - LANDING REVOLUTION LAST DIGIT - RECOVERY AREA AND SUPPORT CAPABILITIES
LAT	\pm XX.X	COORDINATES OF THE DESIRED LANDING AREA
GETI	XXX:XX:XX (HR:MIN:SEC)	DEORBIT IGNITION TIME FOR THE DESIRED LANDING AREA
Δ VC	XXX.X (fps)	DEORBIT MANEUVER Δ V TO BE LOADED INTO THE EMS COUNTER

CSM RENDEZVOUS RESCUE PAD



CSM SEP

33	GETI	XX:XX:XX	TIME OF IGNITION OF SEP (HR.MIN.SEC.)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY
22	R P Y	XXX.XX (DEG) XXX.XX (DEG) XXX.XX (DEG)	NEW ICDO ANGLES

CSM RESCUE ONE

33	GETI	XX:XX:XX	TIME OF IGNITION (HR.MIN.SEC.)
81	SAME AS ABOVE		
22	SAME AS ABOVE		
ΔV_c		XX.X (FPS)	VELOCITY TO BE SET IN EMS COUNTER
11	GETI	XX:XX:XX	TIME OF IGNITION OF CSI (HR.MIN.SEC.)
37	GETI	XX:XX:XX	TIME OF IGNITION OF TPI (HR.MIN.SEC.)

DOI P76 PAD

33	GETI	XX:XX:XX	TIME OF IGNITION (HR.MIN.SEC.)
84	DELTA VX(O VEH) DELTA VY(O VEH) DELTA VZ(O VEH)	XX.X (FPS) XX.X (FPS) XX.X (FPS)	COMPONENTS OF ΔV APPLIED ALONG LOCAL VERTICAL AXIS AT TIG

CSI

11	GETI	XX:XX:XX	TIME OF IGNITION OF CSI (HR.MIN.SEC.)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY.
N		XX	THE FUTURE APSIDAL CROSSING (APOLUNE OR PERILUNE) OF THE ACTIVE VEHICLE AT WHICH CDH SHOULD OCCUR

CDH

13	GETI	XX:XX:XX	TIME OF IGNITION OF CDH (HR.MIN.SEC.)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY

TPI

37	GETI	XX:XX:XX	TIME OF IGNITION OF TPI (HR.MIN.SEC.)
81	DELTA VX DELTA VY DELTA VZ	XX.X (FPS) XX.X (FPS) XX.X (FPS)	LOCAL VERTICAL COMPONENTS OF VELOCITY
59	DELTA V LOS DELTA V LOS 2 DELTA V LOS 3	XX.X (FPS) XX.X (FPS) XX.X (FPS)	DELTA V LINE OF SIGHT COMPONENTS

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P30	P30 LM MANEUVER										P30					
												PURPOSE				
APRIL 1, 1969	+	0	0					+	0	0			HR	N33		
	+	0	0	0				+	0	0	0		MIN	TIG		
	+	0			•			+	0			•	SEC			
						•							•	Δ VX	N81	
						•								•	Δ VY	LOCAL
						•								•	Δ VZ	VERT
	+					•		+						•	Δ VR	
	X	X	X		•			X	X	X		•		BT		
	X	X	X					X	X	X				R	FDAI	
	X	X	X					X	X	X				P	INER	
						•								•	Δ VX	AGS N86
						•								•	Δ VY	AGS
						•								•	Δ VZ	AGS
	X	X	X	X				X	X	X	X			COAS		
	X	X				•		X	X					•	AZ	
X	X				•		X	X					•	EL		
REMARKS:																

P30 LM MANEUVER

PURPOSE		PURPOSE OF MANEUVER (SUCH AS DOI TARGETING)
TIG N33		
HR	XXX	
MIN	XX	IGNITION TIME FOR THE MANEUVER
SEC	XX.XX	
LOCAL VERT		
VX	+XXXX.X (fps)	LOCAL VERTICAL ΔV
ΔVY	+ XXXX.X(FPS)	COMPONENTS OF THE
ΔV	+XXXX.X (fps)	MANEUVER
ΔVR	+XXXX.X(fps)	TOTAL ΔV REQUIRED FOR THE MANEUVER
BT	X:XX(MIN:SEC)	DURATION OF THE MANEUVER
FDAI INER		
R	XXX (DEG)	INERTIAL FDAI ANGLES AT
P	XXX (DEG)	THE BURN ATTITUDE
N86		
VX AGS	+XXXX.X (fps)	LOCAL VERTICAL ΔV
VY AGS	+XXXX.X (fps)	COMPONENTS OF THE
VZ AGS	+XXXX.X (fps)	MANEUVER USED TO
		TARGET THE AGS: ROTATED
		THROUGH THE HALF-ANGLE
		OF THE BURN
COAS	XX(OCTAL)	IDENTIFIER FOR COAS STAR
		USED TO VERIFY SPACECRAFT
		ATTITUDE AT THE BURN
		ATTITUDE
AX	+XX.X (DEG)	THE AZIMUTH AND ELEVATION
EL	+XX.X (DEG)	ANGLES OF THE COAS STAR

		P27 UPDATE															
PURP		V				V				V							
GET		:		:		:		:		:		:					
APRIL 1, 1969	30.6 01	INDEX					INDEX					INDEX					P27
	02																
	03																
	04																
	05																
	06																
	07																
	10																
	11																
	12																
	13																
	14																
	15																
	16																
	17																
	20																
	21																
	22																
	23																
	24																
		N34	HRS	X	X	X					X	X	X				
			MIN	X	X	X	X				X	X	X	X			
		NAV CHECK	SEC	X	X						X	X					
		N43	LAT			0							0				
		LONG															
		ALT	+		0					+		0					

MISSION APOLLO 11 SOURCE FC/BALES

P27 UPDATE

PURP	XXX	TYPE OF DATA TO BE RECEIVED (SUCH AS: NAV-LIFT-OFF TIME)
V	XX	TYPE OF COMMAND LOAD (70 - 71 - 72 - 73)
GET	XXX:XX:XX(HR:MIN:SEC)	TIME DATA RECORDED
306 01	XX(OCTAL)	INDEX NO. OF COMMAND WORDS IN LOAD
02 24	XXXXX	NO. OF CORRECTION COMMAND WORDS
N34 NAV CHECK		TO CONFIRM POINT ABOVE GROUND TRACK FOR A GIVEN TIME
N43	XX:XX:XX(HRS:MIN:SEC)	TIME
LAT	XX:XX(DEG)	LATITUDE
LONG	XXX:XX(DEG)	LONGITUDE
ALT	XXX.X(nm)	ALTITUDE

P76 UPDATE PAD														
												PURPOSE		
	+	0	0					+	0	0		HR	N33	
	+	0	0	0				+	0	0	0	MIN	TIG	
	+	0			•			+	0			SEC		
						•					•	Δ VX	N84	
						•					•	Δ VY		
						•					•	Δ VZ		
													PURPOSE	
		+	0	0					+	0	0		HR	N33
		+	0	0	0				+	0	0	0	MIN	TIG
	+	0			•			+	0			SEC		
						•					•	Δ VX	N84	
						•					•	Δ VY	TIG	
						•					•	Δ VZ		
												PURPOSE		
	+	0	0					+	0	0		HR	N33	
	+	0	0	0				+	0	0	0	MIN	TIG	
	+	0			•			+	0			SEC		
						•					•	Δ VX	N84	
						•					•	Δ VY		
						•					•	Δ VZ		
												PURPOSE		
	+	0	0					+	0	0		HR	N33	
	+	0	0	0				+	0	0	0	MIN	TIG	
	+	0			•			+	0			SEC		
						•					•	Δ VX	N84	
						•					•	Δ VY		
						•					•	Δ VZ		

P76

P76

APRIL 1, 1969

P76 UPDATE PAD

PURPOSE	XXXXXX	PURPOSE OF MANEUVER
N33 GETI	XX:XX:XX	TIME OF IGNITION (HR:MIN:SEC)
N84 DELTA VX(O VEH)	XX.X (FPS)	COMPONENTS OF
DELTA VY(O VEH)	XX.X (FPS)	V APPLIED ALONG
DELTA VZ(O VEH)	XX.X (FPS)	LOCAL VERTICAL AXIS AT TIG (LM VEH)

P32 CSI UPDATE													
	+	0	0				+	0	0			HR	TIG
	+	0	0	0			+	0	0	0		MIN	CSI
	+	0		.			+	0		.		SEC	
	+	0	0				+	0	0			HR	TIG N37
	+	0	0	0			+	0	0	0		MIN	TPI
	+	0		.			+	0		.		SEC	
		0			.			0			.	$\Delta V X$	LOCAL N81
		0	0		.			0	0		.	$\Delta V Y$	VERT
	X	X	X				X	X	X			PLM	FDAI
		0	0		.			0	0		.	$\Delta V X$	AGS N86
		0	0		.			0	0		.	$\Delta V Y$	AGS
		0	0		.			0	0		.	$\Delta V Z$	AGS
	0	0		.			0	0		.	$\Delta V X$	PGNCS N81	
	0	0		.			0	0		.	$\Delta V Y$	LOCAL	
	0	0		.			0	0		.	$\Delta V Z$	VERT	
	0	0		.			0	0		.	$\Delta V X$	CHARTS N81	
X	X	X	X	X	X	X	X	X	X	X	$\Delta V Y$	LOCAL	
X	X	X	X	X	X	X	X	X	X	X	$\Delta V Z$	VERT	
REMARKS:													

APRIL 1, 1969

CSI

CSI

P32 CSI UPDATE

N11 TIG CSI

IGNITION TIME FOR THE
CSI MANEUVER

HR XXX
MIN XX
SEC XX.XX

N37 TIG TPI

IGNITION TIME FOR THE
TPI MANEUVER

HR XXX
MIN XX
SEC XX.XX

N81 LOCAL VERT

ΔV_X $\pm XX.X$ (fps)
 ΔV_Y $\pm XX.X$ (fps)

LOCAL VERTICAL
 ΔV COMPONENTS
OF THE CSI MANEUVER

PLM FDAI

XXX(DEG)

LM FDAI INERTIAL
PITCH ANGLE AT CSI
BURN ATTITUDE

N86

ΔV_X AGS $\pm XX.X$ (fps)
 ΔV_Y AGS $\pm XX.X$ (fps)
 ΔV_Z AGS $\pm XX.X$ (fps)

LOCAL VERTICAL ΔV
COMPONENTS OF CSI
USED TO TARGET AGS
EXT ΔV : ROTATED
THROUGH THE HALF-ANGLE
OF THE BURN

ONBOARD LOG

N81 PGNS LOCAL VERT

ΔV_X $\pm XX.X$
 ΔV_Y $\pm XX.X$
 ΔV_Z $\pm XX.X$

N81 CHARTS LOCAL VERT

ΔV_X $\pm XX.X$

P33 CDH UPDATE														
+ 0 0				+ 0 0				HR						
+ 0 0 0				+ 0 0 0				MIN		TIG CDH				
+ 0				+ 0				SEC						
0				0				ΔVX		N81				
0 0				0 0				ΔVY		LOCAL VERT				
0 0				0 0				ΔVZ						
X X X				X X X				PLM		FDAI				
0				0				ΔVX		AGS N86				
0 0				0 0				ΔVY		AGS				
0 0				0 0				ΔVZ		AGS				
ONBOARD LOG														
0 0				0 0				ΔVX		PGNCS N81				
0 0				0 0				ΔVY		LOCAL VERT				
0 0				0 0				ΔVZ						
0 0				0 0				ΔVX		CHARTS N81				
X X X X X X				X X X X X X				LOCAL VERT						
0 0				0 0				ΔVZ		VERT				
CDH	REMARKS:													CDH
	APRIL 1, 1969													

P33 CDH UPDATE

N13 TIG CDH

IGNITION TIME FOR THE
CDH MANEUVER

HR XXX
MIN XX
SEC XX.XX

N81 LOCAL VERT

ΔV_X $\pm XX.X$ (fps)
 ΔV_Y $\pm XX.X$ (fps)
 ΔV_Z $\pm XX.X$ (fps)

LOCAL VERTICAL ΔV
COMPONENTS OF
THE CDH MANEUVER

PLM FDAI

XXX (DEG)

LM FDAI INERTIAL
PITCH ANGLE AT
CDH BURN ATTITUDE

N86

ΔV_X AGS $\pm XX.X$ (fps)
 ΔV_Y AGS $\pm XX.X$ (fps)
 ΔV_Z AGS $\pm XX.X$ (fps)

LOCAL VERTICAL ΔV
COMPONENTS OF CDH
USED TO TARGET AGS
EXT ΔV ; ROTATED
THROUGH THE HALF-ANGLE
OF THE BURN

ONBOARD LOG

N81 PGNC LOCAL VERT

ΔV_X $\pm XX.X$ (fps)
 ΔV_Y $\pm XX.X$ (fps)
 ΔV_Z $\pm XX.X$ (fps)

N81 CHARTS LOCAL VERT

ΔV_X $\pm XX.X$ (fps)
 ΔV_Z $\pm XX.X$ (fps)

P34 TPI UPDATE														
+ 0 0			+ 0 0			+ 0 0			HR			TIG		
+ 0 0			+ 0 0			+ 0 0			MIN			TPI		
+ 0			+ 0			+ 0			SEC					
									ΔVX			N81		
									ΔVY			LOCAL		
									ΔVZ			VERT		
+ 0 0			+ 0 0			+ 0 0			ΔVR					
X X X			X X X			X X X			RLM			FDAI N42		
X X X			X X X			X X X			PLM			INER		
+ 0			+ 0			+ 0			R TPI			N54		
0			0			0			R TPI			TIG-5		
0 0			0 0			0 0			F/A(+/-)			N59		
0 0			0 0			0 0			R/L(+/-)			ΔV		
0 0			0 0			0 0			D/U(+/-)			LOS		
X X			X X			X X			BT					
ONBOARD LOG														
0 0			0 0			0 0			F/A			PGNCS N59		
0 0			0 0			0 0			R/L			ΔV		
0 0			0 0			0 0			D/U			LOS		
0 0			0 0			0 0			F/A			CHARTS N59		
X X X			X X X			X X X			R/L			ΔV		
0 0			0 0			0 0			D/U			LOS		
REMARKS:														
APRIL 1, 1969														

P34 UPDATE

N37 TIG TPI

HR XXX
MIN XX
SEC XX.XX

IGNITION TIME FOR
THE TPI MANEUVER

N81 LOCAL VERT

ΔV_X $\pm XX.X$ (fps)
 ΔV_Y $\pm XX.X$ (fps)
 ΔV_Z $\pm XX.X$ (fps)
 ΔV_R XX.X (fps)

LOCAL VERTICAL ΔV
COMPONENTS OF THE
TPI MANEUVER

TOTAL ΔV REQUIRED
FOR THE MANEUVER

N42 FDAI INER

R LM XXX (DEG)
P LM XXX (DEG)

LM FDAI ROLL & PITCH
ANGLE AT TPI BURN
ATTITUDE

N54 TIG-5

R TPI XX.XX (FT)
R TPI $\pm XXX.X$ (fps)

RANGE AT TPI TIG -5 MIN
RANGE RATE AT TPI TIG -5 MIN

N59 ΔV LOS

F/A $\pm XX.X$ (fps)
R/L $\pm XX.X$ (fps)
D/U $\pm XX.X$ (fps)
B/T XX:XX

LINE-OF-SIGHT ΔV
COMPONENTS OF THE
TPI MANEUVER

DURATION OF THE MANEUVER
(MINUTES:SECONDS)

ONBOARD LOG

N59 PGNCS ΔV LOS

F/A $\pm XX.X$ (fps)
R/L $\pm XX.X$ (fps)
D/U $\pm XX.X$ (fps)

N59 CHARTS ΔV LOS

F/A $\pm XX.X$ (fps)
R/L
D/U $\pm XX.X$ (fps)

	AGS STATE VECTOR UPDATE														
APRIL 1, 1969												PURP			
														240	
														241	
														242	
														260	
														261	
														262	
		+						+						254	
														244	
														245	
														246	
														264	
														265	
														266	
		+						+						272	
	AGS SV	REMARKS:												AGS SV	

AGS STATE VECTOR UPDATE

PURP		PURPOSE FOR AGS STATE VECTOR UPDATE
240	XXXXX	LM STATEVECTOR-POSITION COMPONENTS
241	XXXXX	
242	XXXXX	
260	XXXXX	LM STATE VECTOR-VELOCITY COMPONENTS
261	XXXXX	
262	XXXXX	
254	XXXXX	LM TIME FOR WHICH THE STATE VECTOR IS ACCURATE
244	XXXXX	CSM STATE VECTOR-POSITION COMPONENTS
245	XXXXX	
246	XXXXX	
264	XXXXX	CSM STATE VECTOR-VELOCITY COMPONENTS
265	XXXXX	
266		
272	XXXXX	CSM TIME FOR WHICH THE STATE VECTOR IS ACCURATE

PDI PAD																
APRIL 1, 1969	+			0	0				+			0	0			HRS
	+			0	0	0			+			0	0	0		MIN TIG
	+			0			•		+			0			•	SEC PDI
	X			X			•		X			X			•	TGO N61
							•									CROSSRANGE
	X			X	X				X			X	X			R FDAI
	X			X	X				X			X	X			P AT TIG
	X			X	X				X			X	X			Y
																DEDA 231 IF RQD
+			0	0				+			0	0			HRS	
+			0	0	0			+			0	0	0		MIN TIG	
+			0			•		+			0			•	SEC PDI	
X			X			•	•	X			X			•	TGO N61	
															CROSSRANGE	
X			X	X				X			X	X			R FDAI	
X			X	X				X			X	X			P AT TIG	
X			X	X				X			X	X			Y	
															DEDA 231 IF RQD	
REMARKS:																
PDI														PDI		

PDI PAD

TIG PDI

TIME OF IGNITION FOR PDI

HRS XXX

MIN XX

SEC XX.XX

N61 TGO XX:XX (HRS:MIN)

TIME TO HIGH GATE

CROSSRANGE +XXXX.X (N.M.)

OUT OF PLANE DISTANCE
BETWEEN LM ORBITAL PLANE
AND LANDING SITE (POSITIVE
INDICATES LANDING SITE IS
NORTH OF ORBITAL PLANE)

FDAI AT TIG

R XXX (DEG)

INERTIAL FDAI ANGLES
AT IGNITION

P XXX (DEG)

Y XXX (DEG)

DEDA 231 XXXXX (100's FT)

LUNAR RADIUS AT THE
LANDING SITE

LUNAR SURFACE	LUNAR SURFACE PAD												LUNAR SURFACE						
		+	0	0	0					+	0	0		0					HRS
	+	0	0	0	0				+	0	0	0	0				MIN		
	+	0	0			•			+	0	0			•			SEC		
	+	0	0	0					+	0	0	0					HRS	T2	
	+	0	0	0	0				+	0	0	0	0				MIN		
	+	0	0			•			+	0	0			•			SEC		
	+	0	0	0					+	0	0	0					HRS	T3	
	+	0	0	0	0				+	0	0	0	0				MIN		
	+	0	0			•			+	0	0			•			SEC		
			•	•		•	•			•	•		•	•			P		
			•	•		•	•			•	•		•	•			(P + Δt)		
	+	0	0	0					+	0	0	0					HRS	TPI	
	+	0	0	0	0				+	0	0	0	0				MIN	N37	
	+	0	0			•			+	0	0			•			SEC		
APRIL 1, 1969	+	0	0	0					+	0	0	0					HRS	T1	
	+	0	0	0	0				+	0	0	0	0				MIN		
	+	0	0			•			+	0	0			•			SEC		
	+	0	0	0					+	0	0	0					HRS	T2	
	+	0	0	0	0				+	0	0	0	0				MIN		
	+	0	0			•			+	0	0			•			SEC		
	+	0	0	0					+	0	0	0					HRS	T3	
	+	0	0	0	0				+	0	0	0	0				MIN		
	+	0	0			•			+	0	0			•			SEC		
				•	•		•	•			•	•		•	•			P	
				•	•		•	•			•	•		•	•			(P + Δt)	
		+	0	0	0					+	0	0	0	0				HRS	TPI
		+	0	0	0	0				+	0	0	0	0				MIN	N37
	+	0	0			•			+	0	0			•			SEC		

LUNAR SURFACE PAD

T1

HRS	XXX	LIFT OFF TIME-FIRST
MIN	XX	PREFERRED TIME AFTER
SEC	XX.XX	TOUCHDOWN (\approx T.D.+4 MIN)

T2

HRS	XXX	LIFT OFF TIME -SECOND
MIN	XX	PREFERRED TIME AFTER
SEC	XX.XX	TOUCHDOWN (\approx T.D. + 11 MIN)

T3

HRS	XXX	LIFT OFF TIME -AFTER
MIN	XX	FIRST CSM REVOLUTION
SEC	XX.XX	

P XXX:XX:XX (HRS:MIN:SEC)

CSM PERIOD

P + Δt XXX:XX:XX (HRS:MIN:SEC)

CSM PERIOD PLUS THE TIME
INTERVAL BETWEEN CLOSEST
APPROACH AND LIFT OFF TIME

TPI

HRS	XXX	TIME OF IGNITION FOR TPI
MIN	XX	AFTER ABORT FROM POWER
SEC	XX.XX	DESCENT

LM ASCENT PAD													
ASCENT	+	0	0				+	0	0			HRS	
	+	0	0	0			+	0	0	0		MIN	TIG
	+	0		•			+	0				SEC	
					•						•	*CROSSRANGE N76	
	X	X	X				X	X	X			R	
	X	X	X				X	X	X			P	FDAI
	X	X	X				X	X	X			Y	AT TIG
	+	0	0				+	0	0			HRS	N11
	+	0	0	0			+	0	0	0		MIN	CSI
	+	0		•			+	0				SEC	
+	0	0				+	0	0			HRS	N37	
+	0	0	0			+	0	0	0		MIN	TPI	
+	0		•			+	0				SEC		
												DEDA 47	
												DEDA 53	
* NOTE: LOAD 8 MI IF CROSSRANGE IS GREATER THAN 8 COMMENTS:													
APRIL 1, 1969													

LM ASCENT PAD

N33 TIG

HRS	XXX	TIME OF IGNITION FOR LM ASCENT
MIN	XX	
SEC	XX.XX	

N76 CROSSRANGE

+XXXX.X (N.M.)

DISTANCE BETWEEN CSM
ORBITAL PLANE AND LM
POSITION VECTOR ON
LUNAR SURFACE (POSITIVE
IS PLANE NORTH OF VECTOR)

FDAI ANGLES AT TIG

R	XXX.XX (DEG)
P	XXX.XX (DEG)
Y	XXX.XX (DEG)

ROLL PITCH AND YAW FDAI
ANGLES AT TIG

N11 CSI

HRS	XXX	TIME OF IGNITION FOR CSI
MIN	XX	
SEC	XX.XX	

N37 TPI

HRS	XXX	TIME OF IGNITION FOR TPI
MIN	XX	
SEC	XX.XX	

DEDA 47

+XXXXX SINE OF AZIMUTH ANGLE

DEDA 53

+XXXXX COSINE OF AZIMUTH ANGLE

SECTION III - DETAILED TIMELINE

SECTION III

FLIGHT PLAN

TIME	EVENT	REMARKS					
-00:09	LCC: <u>REPORT</u> IGNITION	LIFTOFF AT 09:32 EDT, JULY 16, 1969, 72° L.A.					
00:00	LCC: CDR: <u>REPORT</u> LIFT-OFF						
00:02	CDR: <u>REPORT</u> YAW MNVR						
00:11	CDR: <u>REPORT</u> ROLL AND PITCH PROGRAM INITIATE						
00:28	CDR: <u>REPORT</u> ROLL COMPLETE						
00:42	MCC: <u>REPORT</u> MARK MODE IB						
00:50	LMP: <u>REPORT</u> CABIN PRESS DECREASING						
01:17	MAX Q						
01:50	MCC: <u>REPORT</u> MARK MODE IC						
02:00	MCC: CDR: <u>REPORT</u> GO/NO-GO FOR STAGING						
02:14	CDR: <u>REPORT</u> INBOARD ENGINES CUTOFF						
02:40	CDR: <u>REPORT</u> OUTBOARD ENGINES CUTOFF						
02:41	CDR: <u>REPORT</u> STAGING						
02:42	CDR: <u>REPORT</u> S-II IGNITION						
	CMP: <u>REPORT</u> TOWER JETT						
	MCC: <u>REPORT</u> MODE II						
	CDR: <u>REPORT</u> S/C GO/NO-GO						
	MCC: <u>REPORT</u> TRAJECTORY GO/NO-GO						
MISSION	APOLLO 11	EDITION	PRELIMINARY	DATE	APRIL 15, 1969	PAGE	3-i

FLIGHT PLAN

TIME	EVENT	REMARKS
	CMP: <u>REPORT</u> S/C GO/NO-GO	
	LMP: <u>REPORT</u> S/C GO/NO-GO	
	MCC: <u>REPORT</u> S-IVB TO ORBIT CAPABILITY	
	CDR: <u>REPORT</u> S/C GO/NO-GO	
	CDR: <u>REPORT</u> S/C GO/NO-GO	
	MCC: CDR: <u>REPORT</u> S/C GO/NO-GO FOR STAGING	
08:50	CDR: <u>REPORT</u> S-II CUTOFF & S-II S-IVB STAGING	
08:51	CDR: <u>REPORT</u> S-IVB IGNITION	
	CDR: <u>REPORT</u> S/C GO/NO-GO	
	MCC: <u>REPORT</u> TRAJECTORY AND GUIDANCE GO/NO-GO	
	MCC: <u>REPORT</u> MARK MODE IV	
	MCC: CDR: <u>REPORT</u> GO/NO-GO FOR ORBIT	
	MCC: <u>REPORT</u> PREDICTED SECO	
11:21	CDR: <u>REPORT</u> SECO & HP	

MISSION APOLLO 11

EDITION PRELIMINARY

DATE APRIL 15, 1969

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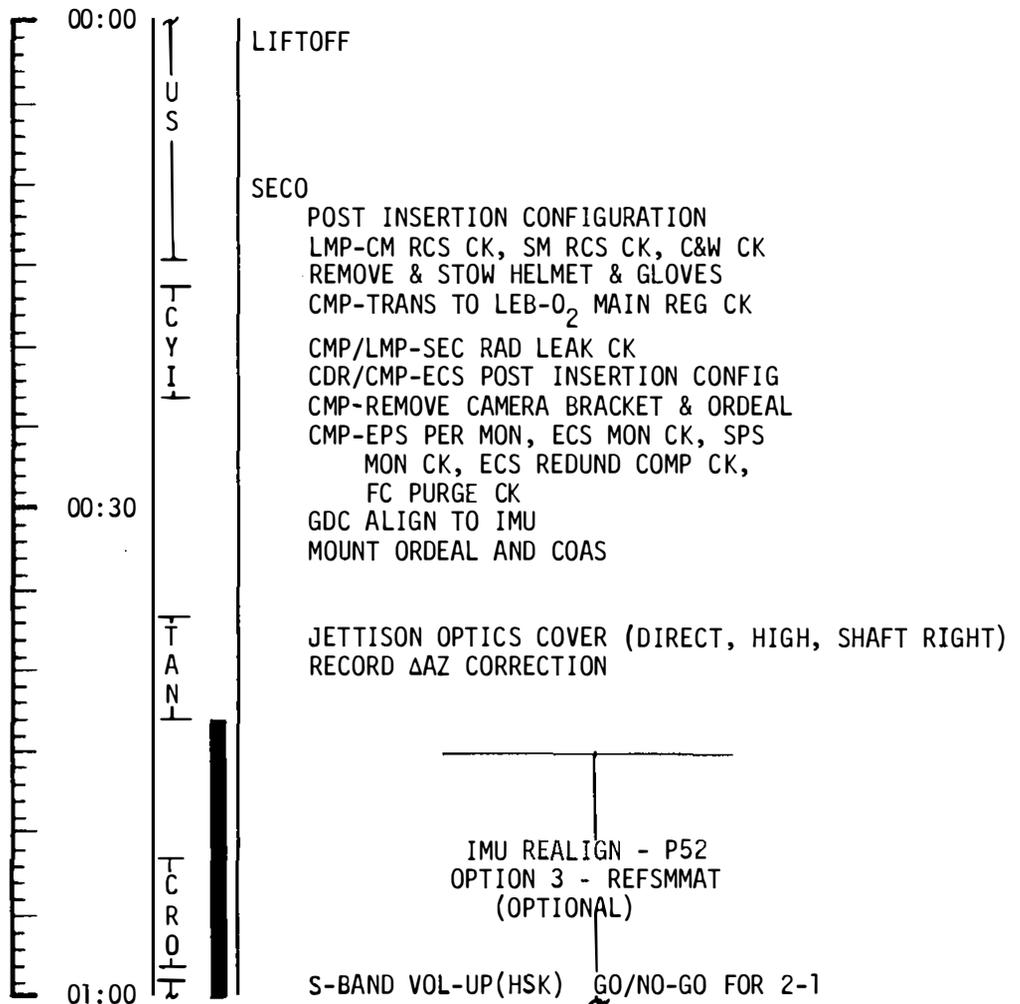
MCC-H
9:30 AM EDT

FLIGHT PLAN

NOTES

VOICE UPDATE:
 Δ AZ CORR

GO/NO-GO



LIFTOFF CREW POSITIONS:
LEFT COUCH - CDR
CENTER COUCH - LMP
RIGHT COUCH - CMP

AT SECO +20 SIV-B MNVRS
TO LH AND INITIALIZES
ORB RATE (HEADS DOWN)

COOLANT CONTROL
ATTENUATION PANEL
NOT OPENED
H₂ PURGE LINE HTR-ON
20 MIN BEFORE FC
PURGE CK

P52 - (PAD REFSMMAT)

N71: _____, _____

N05: _____ . _____

N93:

X _____ . _____

Y _____ . _____

Z _____ . _____

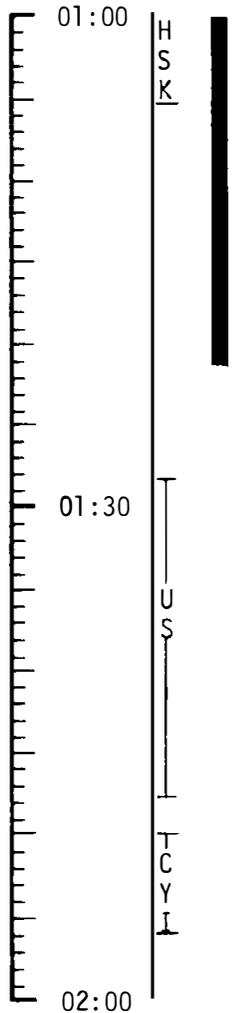
MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
APOLLO 11	PRELIMINARY	APRIL 15, 1969	00:00 - 01:00	1/1	3-1

MCC-H

10:30 AM EDT

FLIGHT PLAN

NOTES



P52 - CONT'D

GDC ALIGN TO IMU

SCS ATT REF COMPARISON CK

RECORD PAD DATA
(TLI, TLI + 90 MIN ABORT, AND
P37 - TLI + 5 HR ABORT)

SM RCS HOT FIRE
(MIN IMPULSE-ALL JETS)

BEGIN TLI PREP CHECK LIST PG. _____

P27 UPDATE:
STATE VECTOR
(CSM & LM)

VOICE UPDATE:
PAD DATA

MON SM RCS HOT
FIRE

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
APOLLO 11	PRELIMINARY	APRIL 15, 1969	01:00-02:00	1/1	3-2

TLI
BURN CHART

	P OR Y RATES	ATT DEVIATION	SHUTDOWN TIME	RESIDUALS
TLI	10°/SEC SHUTDOWN	+45° SHUTDOWN	B/T + 6 SEC & V _i = PAD VALUE	NO TRIM

3-2a

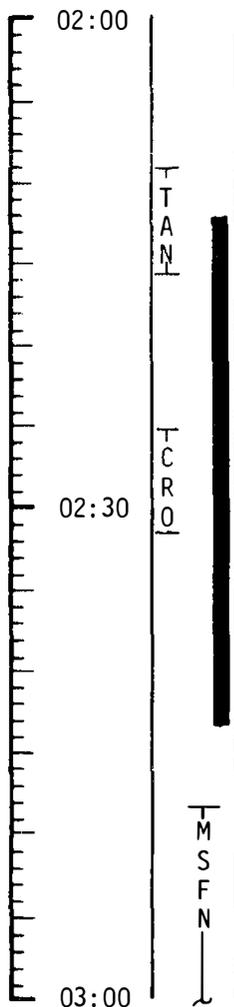
FLIGHT PLAN

NOTES

MCC-H

11:30 AM EDT

GO/NO-GO



EMS ΔV TEST
DON HELMET AND GLOVES

GO/NO GO FOR TLI & PYRO ARM
GDC ALIGN & DRIFT CK

P47 - THRUST MONITOR

TLI

GETI: 2:44:18
BT: 5:21
ΔV:

V66-TRANS CSM STATE VECTOR TO LM SLOT
 TLI BURN STATUS REPORT
 CDR-TRANS TO CENTER COUCH, CMP-LEFT COUCH, LMP-RIGHT COUCH

CMP-UNSTOW AND PREPARE
 CAMERA EQUIP
 WASTE VENT VALVE - CLOSED
 PRESS CM TO 5.7 PSIA

SEQ/18/CEX-BRKT (F11,250,INF) 6 fps 1 MAG EL/80/CEX(F11,250,INF) (fps AT CREW OPTION)

AT SECO: SIVB INERTIAL
 AT SECO + 20 SEC: SIVB
 TO LH, ORB RATE, HEADS
 DOWN

CREW POSITIONS:
 LEFT COUCH - CMP
 CENTER COUCH - CDR
 RIGHT COUCH - LMP

MISSION	EDITION	DATE	TIME	DAY/REV	PAGE
APOLLO 11	PRELIMINARY	APRIL 15, 1969	02:00-03:00	1/2	3-3

FLIGHT PLANNING BRANCH

MSC Form 29 OT (Mar. 69)